

Toward Corruption

The progress of science is marked by the transformation of the qualitative into the quantitative. In this way not only do notions become turned into theories and lay themselves open to precise investigation, but the logical development of the notion becomes, in a sense, automated. Once a notion has been assembled mathematically, then its implications can be teased out in a rational, systematic way. Now, we have promised that this account of the Second Law will be nonmathematical, but that does not mean we cannot introduce a quantitative concept. Indeed, we have already met several, temperature and energy among them. Now is the time to do the same thing for spontaneity.

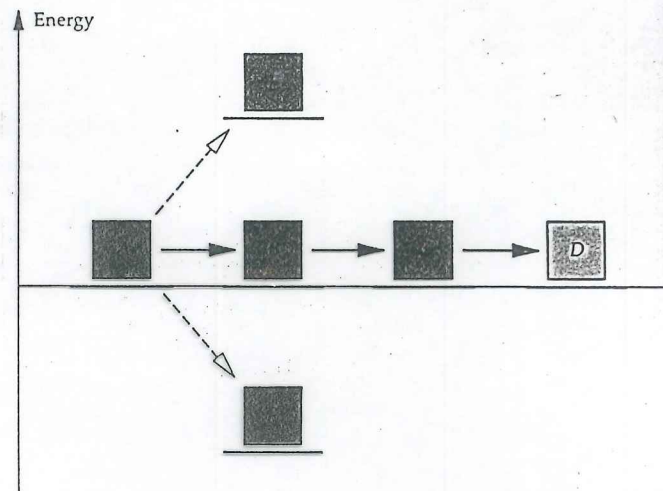
* The idea behind the next move can be described as follows. The Zeroth Law of thermodynamics refers to the thermal equilibrium between objects ("objects," the things at the center of our attention, are normally referred to as systems in thermodynamics, and we shall use that term from now on). Thermal equilibrium exists when system A is put in thermal contact with system B, but no net flow of energy occurs. In order to express this condition, we need to introduce the idea of the temperature of a system, which we define as meaning that if A and B happen to have the same temperature, then we know without further ado that they are in thermal equilibrium with each other. That is, the Zeroth Law gives us a reason to introduce a "new" property of a system, so that we can easily decide whether or not that system would be in thermal equilibrium with any other system if they were in contact.

* The First Law gives us a reason to carry out a similar procedure, but now one that leads to the idea of "energy." We may be interested in what states a system can reach if we heat it or do work on it. We can assess whether a particular state is accessible from the starting condition by introducing the concept of energy. If the new state differs in energy from the initial state by an amount that is different from the quantity of work or heating that we are doing, then we know at once, from the First Law, that that state cannot be reached: we have to do more or less work, or more or less heating, in order to bring the energy up to the appropriate value. The energy of a system is therefore a property we can use for deciding whether a particular state is accessible (see figure on next page).

This suggests that there may be a property of systems that could be introduced to accommodate what the Second Law is telling us. Such a property would tell us, essentially at a glance, not whether one state of the system is accessible from the other (that is the job of the energy acting through the First Law), but whether it is spontaneously accessible. That is, there ought to be a property that can act as the signpost of natural, sponta-



An isolated system may in principle change its state to any other of the same energy (the four colored boxes in the horizontal row), but the First Law forbids it to change to states of different energy (the brown-tinted boxes).



neous change, change that may occur without the need for our technology to intrude into the system in order to drive it.

* There is such a property. It is the entropy of the system, perhaps the most famous and awe-inspiring thermodynamic property of all. Awe-inspiring it may be: but the awe should not be misplaced. The awe for entropy should be reserved for its power, not for its difficulty. The fact that in everyday discourse "entropy" is a word far less common than "energy" admittedly makes it less familiar, but that does not mean that it stands for a more difficult concept. In fact, I shall argue (and in the next chapter hope to demonstrate) that the entropy of a system is a simpler property to grasp than its energy! The exposure of the simplicity of entropy, however, has to await our encounter with atoms. Entropy is difficult only when we remain on the surface of appearances, as we do now.

Entropy

We are now going to build a working definition of entropy, using the information we already have at our disposal. The First Law instructs us to think about the energy of a system that is free from all external influences; that is, the constancy of energy refers to the energy of an *isolated system*, a system into which we cannot penetrate with heat or with work, and which for brevity we shall refer to as the *universe* (see figure on facing page). Similarly, the entropy we define will also refer to an isolated system, which we shall call the universe. Such names reflect the hubris of thermodynamics: later we shall see to what extent the "universe" is truly the Universe.

de biología social; pero la tendencia actual a considerar los australopitecos y parántropos como «chimpancés bípedos», es decir, vegetarianos, sin tecnología lítica, ni aumento cerebral importante, ni lenguaje, y con un desarrollo rápido, sitúa este gran cambio dentro del género *Homo*.

"LA ESPECIE ELEGIDA"

ISBN 84-7880-909-0 (1998)

Tamaño del cerebro y tamaño del grupo social

En otro capítulo de este libro nos hemos preguntado para qué sirve ser bípedo, es decir, qué tipo de adaptación es ésta y con qué nicho ecológico está relacionada. Ya vimos que la respuesta no es fácil. Sin embargo, nadie se pregunta para qué sirve ser inteligente. Estamos tan convencidos de que la inteligencia es un don que nos hace superiores a cualquier otra forma viviente que no nos preocupamos por su valor adaptativo. Sin embargo, la expansión cerebral es una especialización como la de cualquier otro órgano, y la selección natural la ha favorecido porque presentaba ventajas en el contexto del nicho ecológico de los homínidos en los que se produjo (que no fueron todos, como se ha visto). ¿Cuáles fueron esas ventajas?

Hay dos momentos de la evolución humana en los que se produce una marcada expansión del tamaño cerebral, que podría ponerse en relación con cambios significativos en las pautas sociales. La primera de estas expansiones se produce con el *Homo ergaster*, donde el volumen cerebral pasa de representar aproximadamente un tercio del valor promedio de nuestra especie, como en los australopitecos y parántropos, a llegar hasta los dos tercios (el *Homo habilis* ocuparía una posición intermedia). La segunda gran expansión tiene lugar en el último medio millón de años, y produce los enormes cerebros de nuestra especie y de los neandertales.

↓ El aumento del volumen cerebral comporta, como hemos visto, un cambio en la alimentación, porque afecta a un tejido energéticamente costoso. En consecuencia, se incorporan a la dieta en cantidades sustanciales las proteínas y grasas animales. A diferencia de algunos vegetales muy abundantes (aunque poco energéticos), estos recursos no se distribuyen de manera continua en el medio, ni son fáciles de obtener, por lo que aumenta el tamaño del territorio a

recorrer y el tiempo de búsqueda. Al mismo tiempo, desde el *Homo ergaster* los ritmos de crecimiento se sitúan ya próximos a los nuestros, lo que supone un periodo de dependencia infantil más prolongado que en antropomorfos y homínidos anteriores. Todo esto implica que difícilmente una madre podría hacerse cargo, ella sola, de varias crías al mismo tiempo. Por este motivo es posible que el gran cambio social se produjera en el *Homo ergaster*, aunque algunos autores sostienen que tuvo lugar en la segunda gran expansión cerebral, la nuestra y la de los neandertales.

Pero no sólo existe una relación indirecta entre el aumento de tamaño del cerebro y las relaciones entre los dos sexos, sino que es posible que la expansión cerebral esté directamente asociada a un aumento de la complejidad social. En primer lugar, se ha observado que los mamíferos que viven en sociedades complejas (como simios y delfines) tienen cerebros mayores que los mamíferos solitarios de tamaño similar. Aiello y Dunbar han descubierto también que entre las diferentes especies de primates el tamaño relativo del neocórtex respecto del resto del encéfalo está en función directa del tamaño de los grupos sociales que forman esas mismas especies.

Sin embargo, no se ha encontrado una relación similar entre el tamaño relativo del neocórtex y el tipo de vida, por lo que la «teoría ecológica» del origen de nuestra muy desarrollada inteligencia pierde fuerza respecto de la «teoría social»; no obstante, no hay que perder de vista que a partir de los primeros *Homo* los homínidos entraron en un nicho ecológico totalmente nuevo para los primates, el de carroñeros y cazadores, que también pudo favorecer el desarrollo intelectual.

En resumen, es una teoría muy respetable la de que la expansión del cerebro y de la inteligencia (o al menos una parte sustancial de la misma) representa una adaptación a la vida social, un medio en el que uno tiene que cooperar y competir a la vez con los mismos individuos. Una inteligencia desarrollada con estos propósitos (una «inteligencia social») podría muy bien aplicarse a otro tipo de situaciones complejas. Para prosperar en ese difícil medio social hace falta utilizar diversas tácticas, que van desde la formación de alianzas con otros individuos, basadas en el parentesco o en el interés, hasta el engaño. Anne Pusey, Jennifer Williams y Jane Goodall han observa-



La Ley de la Entropía y el proceso económico (1971)

Nicholas Georgescu-Roegen
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FUNDACIÓN
ARGENTARIA



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(distribuciones/sa)

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TERMODINAMIKAREN BIGARREN PRINTZIBIOA

* 1. ZADIKO ASIMETRIA

6.1, 6.6

6.5

6.7

• Atkins

- LANA/BEROA ; BEROA/LANA TRANSFORMAZIO-MOTAK
- ZIKLOAK ETA MOTORE TERMIKOAK : MOTOREAK, HOSKAILUAK, PUNTAK, ETEKINAK, EFIZIENTZIAK
- BIGARREN PRINTZIBIOAREN ENUNTZIATUA
 - CLAUSIUS-EN ENUNTZIATUA
 - KELVIN/PLANCK-EN ENUNTZIATUA
- BIGARREN PRINTZIBIOAREKIN LOTURIK DAGOEN ALDAGAI TERMODINAMIKOA

7.1

* ITZULGARRITASUNA / ITZULEZINTASUNA

7.2

7.3

7.4

7.5

7.6

* BIGARREN PRINTZIBIOAREN ONDORIOAK

- 1 - 1. ZADIKO BEREZKO PROZESUAK ITZULEZINAK DIRA (ADIBIDEAK)
 - ITZULGARRITASUNERAKO BALDINTZAK
 - ONDORIOEKIN SEGITZKO BI METODO:

AXIOMATIKOA : CARATHÉODORY-REN ENUNTZIATUA

7.7

7.8

7.9

7.10, 7.11

8.1

8.2

8.3

8.4

2

3

4

5 (2')

- GAINAZAL ADIABATIKO ITZULGARRIEN EXISTENTZIA
- SG-REN FAKTORE INTEGRATZAILA : ESANGURA FISIKOA
- KELVIN TEMPERATURA-ESKALA

KELVIN TEMPERATURA-ESKALA = GAS IDEALAREN

- ENTROPIA FUNTZIOAREN EXISTENTZIA *adibideak kalkkula*

TEKNIKOA : KELVIN, PLANCK-EN METODOA

8.5

8.6

4

5 (2')

- CARNOT-EN ZIKLOA
- CARNOT MOTOREAREN ETEKINAK : SISTEMAREKIKO MENPEKOTASUNIKETZ BALIOKIK ALTUENA
- KELVIN TEMPERATURA-ESKALA
- CLAUSIUS-EN TEOREMA : ENTROPIA FUNTZIOAREN EXISTENTZIA

8.8

* ENTROPIA-FUNTZIOAREN PRINTZIBIOA

- BIGARREN PRINTZIBIOAREN FURMUZAZIO BERRIA

8.9

8.10

8.11 (2.p)

* LAN MAXIMOAREN TEOREMA

- ERABIL DAITZEEN ENERGIA

+ C. 4. GAIA : 4.5 1-1
4.7 C2

4.1
4.2
4.3
4.4

IZADIKO ASIMETRIA (EXPERIENTZIAREN ARABERA)

(i) - LANA $\rightarrow$ BEROA TRANSFORMAZIO-MOTAK (EDOZEIN LAN-MOTA)

ADIBIDEA

EZAUGARRIAK : (1) - % 100

(2) - SISTEMAREN ESPERA ALDATU GABE

(3) - BEHIN ETA BERRIRO ("AD INFINITUM")

} ALDIBEREAN

(ii) - BEROA $\rightarrow$ LANA TRANSFORMAZIO-MOTAK (EDOZEIN LAN-MOTA)

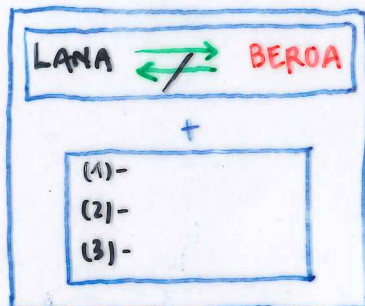
ADIBIDEA

EZAUGARRIAK : (1) - % 100

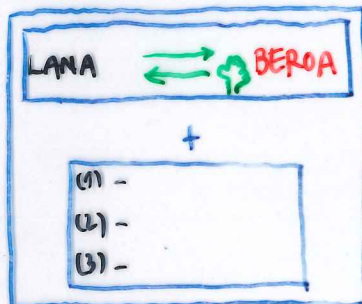
(2) - SISTEMAREN ESPERA ALDATU GABE

(3) - BEHIN ETA BERRIRO ("AD INFINITUM")

} ERINEZKOR
ALDIBEREAN



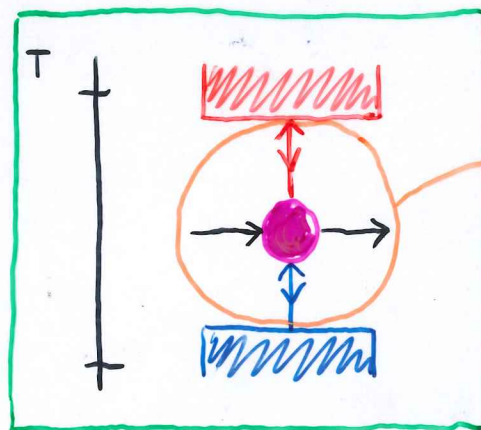
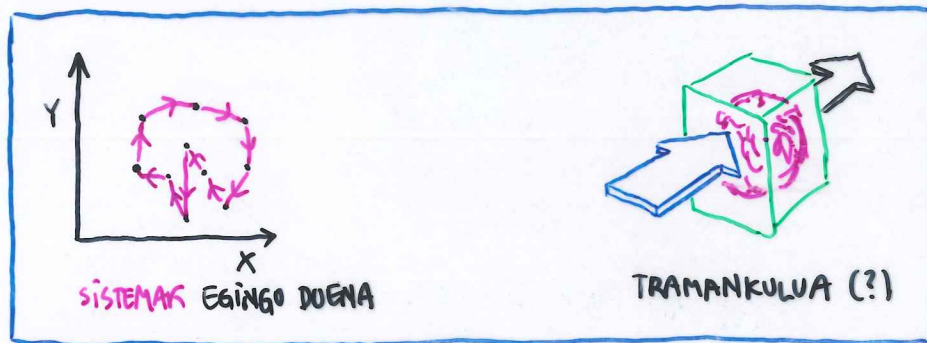
ASIMETRIA!!



SIMETRIA!!

$\rightleftharpoons$ = INGURUNEAREKIN LOTU
(ALDIBEREAN HIRURAK LOTURAKO
MOTOREAK BEHAR DIRA)

ZIKLOAK ETA MAKINA TERMIKOAK

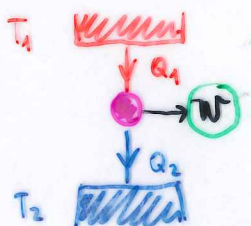


LEHENENGO PRINTEZIOA

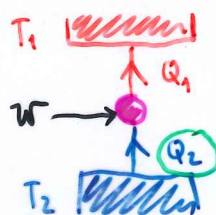
$$Q = \Delta U - W \quad \Delta U = 0$$

$$Q = -W$$

MOTORE TERMIKOA

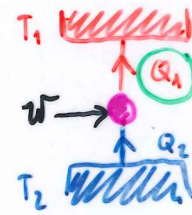


HOTZAILUA



$$|Q_1| - |Q_2| = |W|$$

BERO-PUNPA



$$\eta = \frac{|W|}{|Q_1|} = \frac{|Q_1| - |Q_2|}{|Q_1|} = 1 - \frac{|Q_2|}{|Q_1|}$$

$$\epsilon_h = \frac{|Q_1|}{|W|} = \frac{|Q_1|}{|Q_1| - |Q_2|} = \frac{1}{\frac{|Q_2|}{|Q_1|} - 1}$$

$$\epsilon_p = \frac{|Q_1|}{|W|} = \frac{|Q_1|}{|Q_1| - |Q_2|} = \frac{1}{1 - \frac{|Q_2|}{|Q_1|}}$$

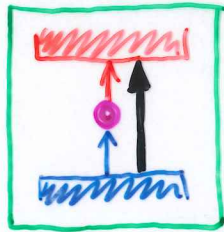
Adierazpena modu

$$\epsilon_p = \frac{|Q_1|}{|W|} = \frac{|Q_1|}{|Q_1| - |Q_2|}$$

TERMODINAMIKAREN BIGARREN PRINTZPIOAREN ENUNTZIATUAK

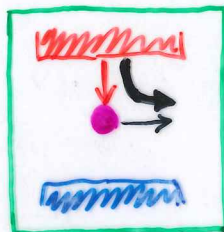
(1)- CLAUSIUS-EN ENUNTZIATUA (DENOK EZAGUTU DUGUNA)

EZ DAGO PROZESURIK ZEINAREN **ONDORIO BAKARRA*** GORPUTZ HOTZETIK GORPUTZ BERURAKO BERO-TRANSFERENTZIA DEN



(2)- KELVIN/PLANCK-EN ENUNTZIATUA (MOTOREAK BEHAR DIRA)

EZ DAGO PROZESURIK ZEINAREN **ONDORIO BAKARRA*** GORPUTZ BEROTIK HARTUTAKO BERO GUZTIA LAN BIHURTZEAREN DEN



ASIMETRIA BERAREN BI (BADAHO GERTAGORRIK) AURPEGIAK
BADAHO BESTE ENUNTZIATURIK

* "... BESTE INOLAKO ERAGINIK GABE."

"... BESTE SISTEMAREN BATEAN ERAGINIK IZAN GABE."

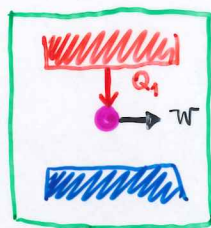
"... ESKUARTU GABE."

BIGARREN PRINTZPIOAREKIN LOTURIK DAGOEN ALDAGAI TERMODINAMIKOA: ENTROPIA

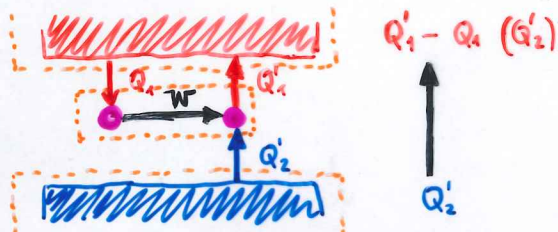
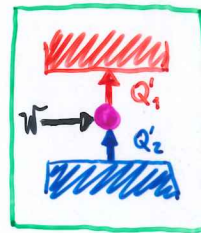
S

ENUNTZIATUEN ARTEKO BALIOKIDETASUNA : $C \Leftrightarrow K/P$

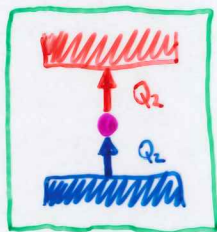
(i) $(C \Rightarrow K/P) \Rightarrow \boxed{Ez K/P \Rightarrow Ez C}$



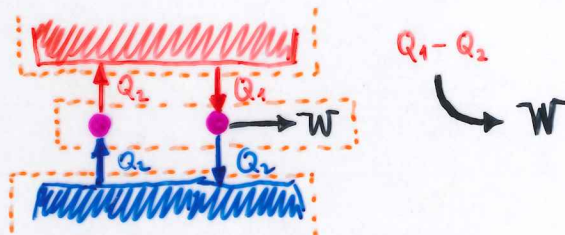
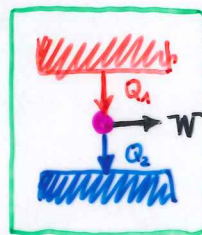
+



(ii) $(K/P \Rightarrow C) \Rightarrow \boxed{Ez C \Rightarrow Ez K/P}$

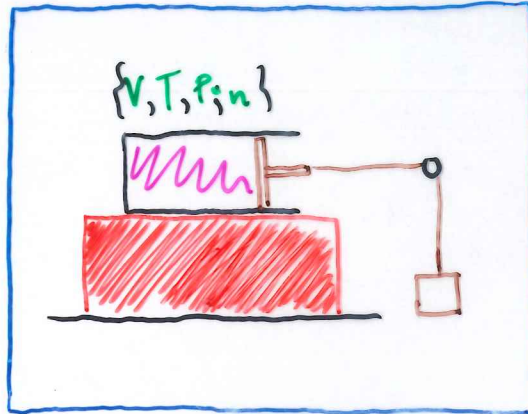


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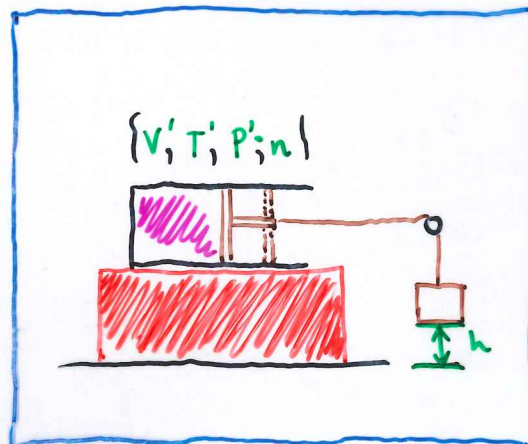
ITZULGARITASUNA/ ITZULEZINTASUNA

(i)



HASIERAKO OREKA-EGOKERA

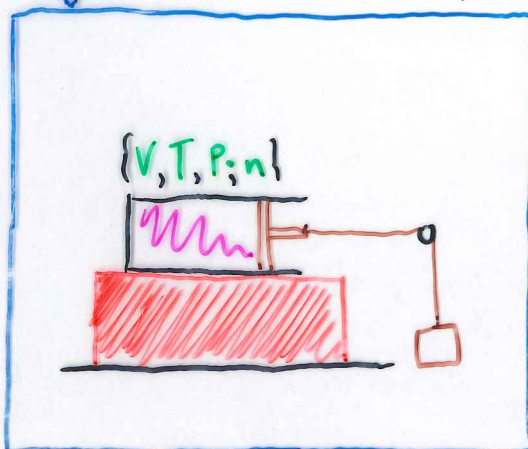
(f)



BUKAEAKO OREKA-EGOKERA

SISTEMAK : ENERGIA
BERO-ITURRIAK : BEROA
LAN-FOKOAK : LANA

(i)



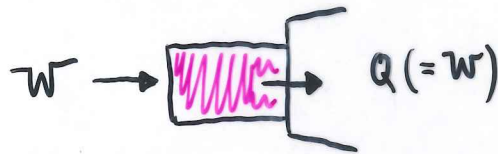
BESTE INOLAKO
ERAGINIK IZAN GABE!!

KONEXIOK GABE!!

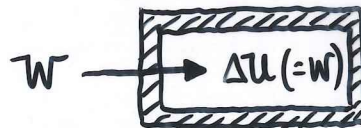
?? GABE!!

BIGARREN PRINTZÍPIOAREN ONDORIOAK :

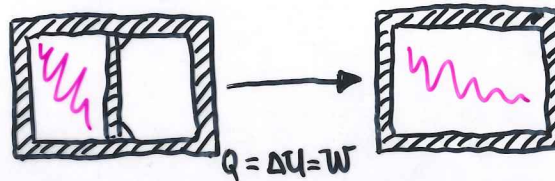
(1) - IZADIKO **BEREZKO** PROZESUAK ("PROZESU ESPONTANEOAK") ITZULEZINAK DIRA.



BERO-TIRARIAREN BARNE-ENERGIA



SISTEMAREN BARNE-ENERGIA



ESPANTATIA ASKEA



BERO-KONDUKZIOA

ITZUGARRITASUNERAKO * BALDINTZAK :

- (a) EZ DAGO OREKA TERMODINAMIKORIK
- (b) ENERGIA - BARREIAPENA (DISIPAZIOA)

PROZESU ITZUGARRIA

$\Leftrightarrow$

{ KUASIESTATIKOA
BARREIAPENIK GABEKOA

METODO AXIOMATIKOA

CARATHEODORY-REN ENUNTZIATUA

EDOZEIN SISTEMAREN, EDOZEIN OREKA-EGOKERAREN INGURUAN,
PROZESU ADIABATIKO ITZULGARRIEN BIDEZ LOTU EZIN DIREN
OREKA-EGOKERAK DAUDE


EZ (ADIABATIKO ITZULGARRI)

(2) - GAINAZAL ADIABATIKO ITZULGARRIEN EXISTENTZIA : (GAIEN EXISTENTZIA)

(i) - OSAGAIA BAKARRERAKO SISTEMA :

$$\{t, Y, X\} \Rightarrow f(t, Y, X) = 0 \Rightarrow Y = Y(t, X)$$

$$\delta Q = dU - \delta W$$
$$\delta W = Y dX$$

$$\delta Q = dU - Y dX$$
$$dU = \left(\frac{\partial U}{\partial t}\right)_X dt + \left(\frac{\partial U}{\partial X}\right)_t dX$$

$$\delta Q = \left(\frac{\partial U}{\partial t}\right)_X dt + \left[\left(\frac{\partial U}{\partial X}\right)_t - Y\right] dX$$

$$\delta Q = 0$$

$$\left(\frac{\partial U}{\partial t}\right)_X dt + \left[\left(\frac{\partial U}{\partial X}\right)_t - Y\right] dX = 0$$

$$\left(\frac{\partial U}{\partial t}\right)_X dt = \left[Y - \left(\frac{\partial U}{\partial X}\right)_t\right] dX$$

$$\left[\frac{dt}{dX}\right] = \left[\frac{Y - \left(\frac{\partial U}{\partial X}\right)_t}{\left(\frac{\partial U}{\partial t}\right)_X}\right]$$

$$\sigma = \sigma(t, X) = Kt$$

inorkin :

lehenergo printzipiaren
adierazpena prozesu
itzulgarriaren kasuan.
eta anvekolatan ?

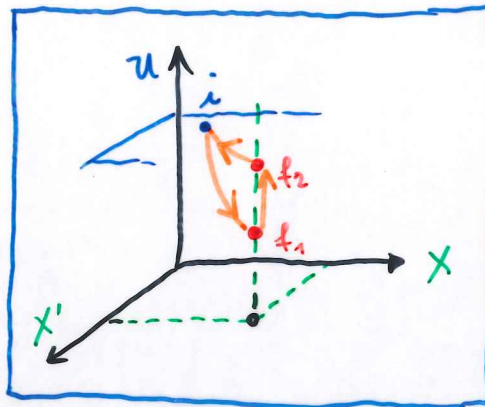
(ii) ALDAGAI ANITZEKO SISTEMA :

$$\{t, Y, X, Y', X'\} \rightarrow f(t, Y, X) = 0 \Rightarrow Y = Y(t, X)$$

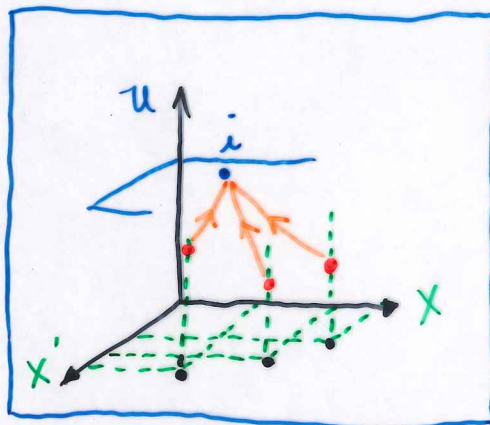
$$f'(t, Y', X') = 0 \Rightarrow Y' = Y'(t, X')$$

$$t = t(u, X, X', Y, Y')$$

$$\delta Q = dU - Y dX - Y' dX'$$



EZINEZKOA !!!



$$\sigma = \sigma(t, X, X') = Kt$$

$$\sigma = \sigma(t, X, X')$$

GAINAZAL ADIABATIKO ITZULGARRIA

(3) δQ - REN FAKTORE INTEGRATEAILEA (2. INDORIOAREN ONDORIOA)

$$\delta Q = dU - Ydx - Y'dx' \quad \left\{ \begin{array}{l} u = u(t, x, x') \\ Y = Y(t, x, x') \\ Y' = Y'(t, x, x') \end{array} \right\}$$

$$\sigma = \sigma(t, x, x') \Rightarrow t = t(\sigma, x, x')$$

$$\delta Q = \left(\frac{\partial u}{\partial \sigma} \right)_{x, x'} d\sigma + \left[\left(\frac{\partial u}{\partial x} \right)_{\sigma, x'} - Y \right] dx + \left[\left(\frac{\partial u}{\partial x'} \right)_{\sigma, x} - Y' \right] dx'$$

$$(i) \quad d\sigma = dx = 0 \\ dx' \neq 0$$

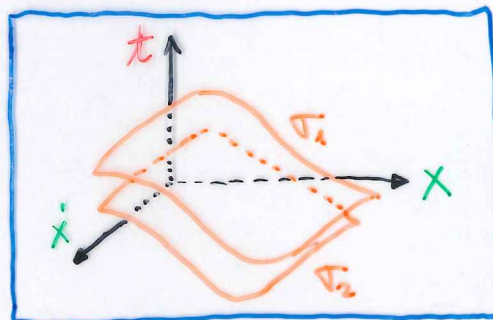
$$(ii) \quad d\sigma = dx' = 0 \\ dx \neq 0$$

$$\delta Q = \left(\frac{\partial u}{\partial \sigma} \right)_{x, x'} d\sigma$$

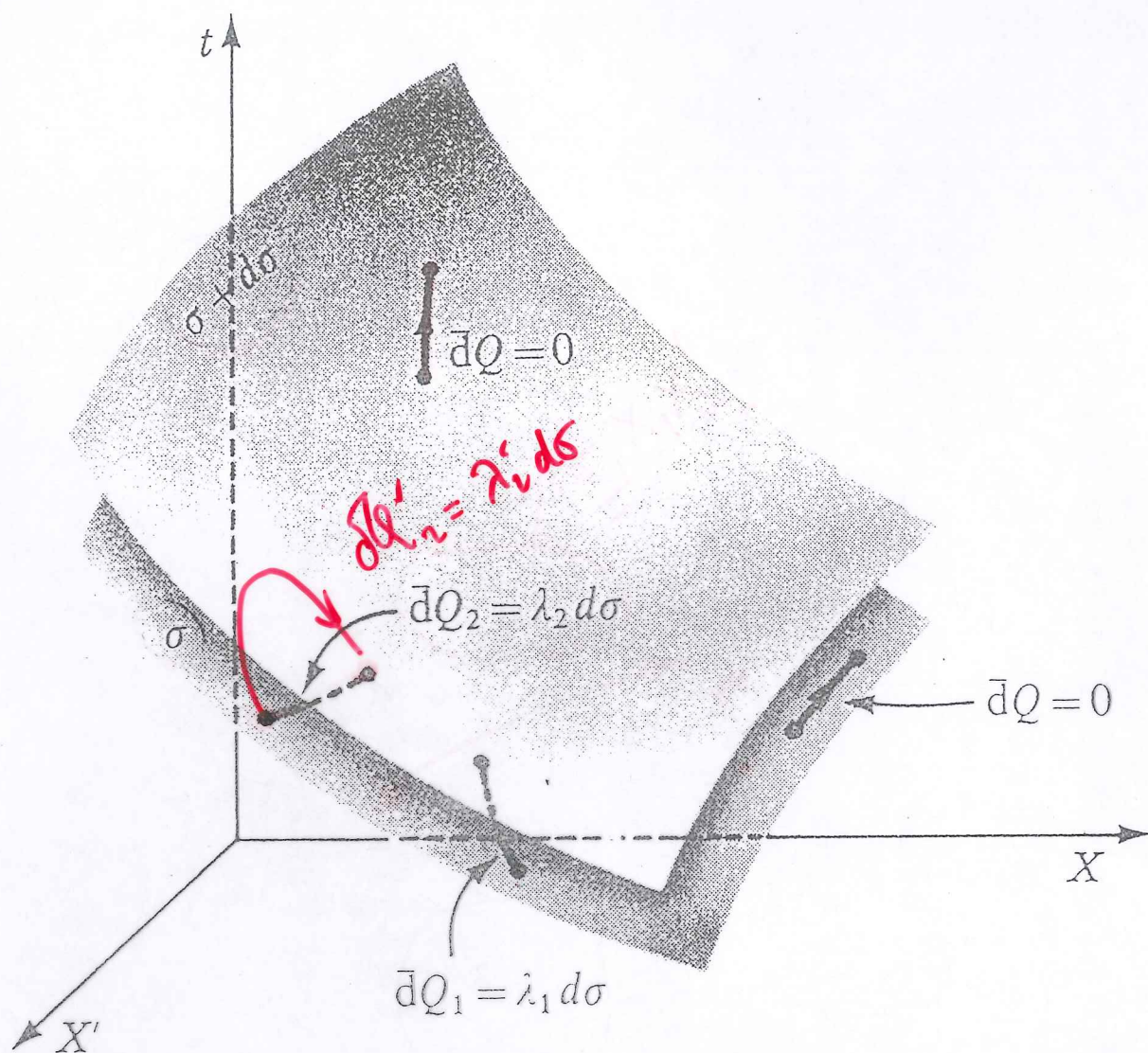
$$\lambda \equiv \left(\frac{\partial u}{\partial \sigma} \right)_{x, x'}$$

$$\delta Q = \lambda d\sigma$$

$$\lambda = \lambda(\sigma, x, x')$$



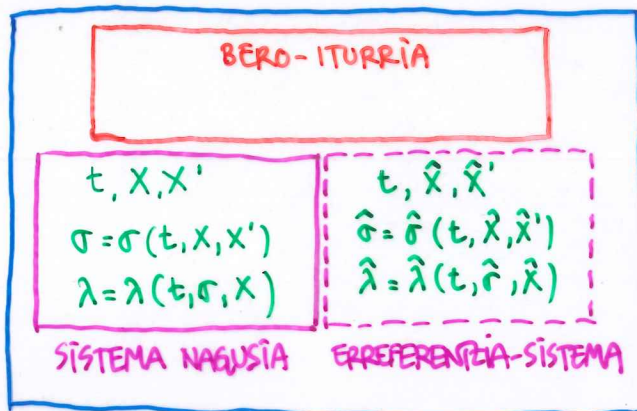
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FAKTORE INTEGRATZAILEAREN ESANGURA FISIKOA

ALDAGAI INDEPENDENTEAK
GAINAZAL ADIABATIKO ITQ.
FAKTORE INTEGRATZAILEA



SISTEMA KONPOSATUA

$$(t, X, X', \hat{X}, \hat{X}') \rightarrow \{t, \sigma, X, \hat{\sigma}, \hat{X}\}$$

$$\bar{\sigma} = \bar{\sigma}(t, \sigma, X, \hat{\sigma}, \hat{X})$$

$$\bar{\lambda} = \bar{\lambda}(t, \sigma, X, \hat{\sigma}, \hat{X})$$

$$\delta \bar{Q} = \delta Q + \delta \hat{Q}$$

$$\bar{\lambda} d\bar{\sigma} = \lambda d\sigma + \hat{\lambda} d\hat{\sigma}$$

$$d\bar{\sigma} = \frac{\lambda}{\bar{\lambda}} d\sigma + \frac{\hat{\lambda}}{\bar{\lambda}} d\hat{\sigma}$$

$$\bar{\sigma} \rightarrow \bar{\sigma} + d\bar{\sigma}$$

$$d\bar{\sigma} = \left(\frac{\partial \bar{\sigma}}{\partial t} \right)_{\sigma, X, \hat{\sigma}, \hat{X}} dt + \left(\frac{\partial \bar{\sigma}}{\partial \sigma} \right)_{t, X, \hat{\sigma}, \hat{X}} d\sigma + \left(\frac{\partial \bar{\sigma}}{\partial X} \right)_{t, \sigma, \hat{\sigma}, \hat{X}} dX + \left(\frac{\partial \bar{\sigma}}{\partial \hat{\sigma}} \right)_{t, X, \sigma, \hat{X}} d\hat{\sigma} + \left(\frac{\partial \bar{\sigma}}{\partial \hat{X}} \right)_{t, \sigma, X, \hat{\sigma}} d\hat{X}$$

$$\delta Q = \lambda d\sigma \Rightarrow \delta Q = \phi(t) f(\sigma) d\sigma$$

- FAKTORE INTEGRATZAILEA (SISTEMA)
- TEMPERATURAREN FUNTzioA SOILIK
- FUNTzio UNIBERTSALA

(1)

$$\delta \bar{Q} = \delta Q + \delta \hat{Q}$$

$$\delta Q = \lambda d\sigma$$

adiversionen overkomme

$$\bar{\lambda} d\bar{\sigma} = \delta \bar{Q} = \lambda d\sigma + \hat{\lambda} d\hat{\sigma}$$

$$d\bar{\sigma} = \frac{\lambda}{\bar{\lambda}} d\sigma + \frac{\hat{\lambda}}{\bar{\lambda}} d\hat{\sigma}$$

$$\Rightarrow \bar{\sigma} = \bar{\sigma}(\sigma, \hat{\sigma}) \Rightarrow d\bar{\sigma} = \left(\frac{\partial \bar{\sigma}}{\partial \sigma}\right)_{\hat{\sigma}} d\sigma + \left(\frac{\partial \bar{\sigma}}{\partial \hat{\sigma}}\right)_{\sigma} d\hat{\sigma} \Rightarrow \left\{ \begin{array}{l} \left(\frac{\partial \bar{\sigma}}{\partial \sigma}\right)_{\hat{\sigma}} = \frac{\lambda}{\bar{\lambda}} \\ \left(\frac{\partial \bar{\sigma}}{\partial \hat{\sigma}}\right)_{\sigma} = \frac{\hat{\lambda}}{\bar{\lambda}} \end{array} \right\} = \left. \begin{array}{l} = g_1(\sigma, \hat{\sigma}) \\ = g_2(\sigma, \hat{\sigma}) \end{array} \right\}$$

(2)

$$\bar{\sigma} = \bar{\sigma}(t, \sigma, \hat{\sigma}, x, \hat{x})$$

$$d\bar{\sigma} = \left(\frac{\partial \bar{\sigma}}{\partial t}\right)_{\sigma, \hat{\sigma}, x, \hat{x}} dt + \left(\frac{\partial \bar{\sigma}}{\partial \sigma}\right)_{t, \hat{\sigma}, x, \hat{x}} d\sigma + \left(\frac{\partial \bar{\sigma}}{\partial \hat{\sigma}}\right)_{t, \sigma, x, \hat{x}} d\hat{\sigma} + \left(\frac{\partial \bar{\sigma}}{\partial x}\right)_{t, \sigma, \hat{\sigma}, \hat{x}} dx + \left(\frac{\partial \bar{\sigma}}{\partial \hat{x}}\right)_{t, \sigma, \hat{\sigma}, x} d\hat{x}$$

haverik alderafu

ondurisa

$$\left(\frac{\partial \bar{\sigma}}{\partial t}\right)_{\sigma, \hat{\sigma}, x, \hat{x}} = \left(\frac{\partial \bar{\sigma}}{\partial x}\right)_{t, \sigma, \hat{\sigma}, \hat{x}} = \left(\frac{\partial \bar{\sigma}}{\partial \hat{x}}\right)_{t, \sigma, \hat{\sigma}, x} = 0$$

$$d\bar{\sigma} = \left(\frac{\partial \bar{\sigma}}{\partial \sigma}\right)_{t, \hat{\sigma}, x, \hat{x}} d\sigma + \left(\frac{\partial \bar{\sigma}}{\partial \hat{\sigma}}\right)_{t, \sigma, x, \hat{x}} d\hat{\sigma} \Rightarrow \left(\frac{\partial \bar{\sigma}}{\partial \sigma}\right)_{t, \hat{\sigma}, x, \hat{x}} = f_1(t, \sigma, \hat{\sigma}, x, \hat{x}) ; \left(\frac{\partial \bar{\sigma}}{\partial \hat{\sigma}}\right)_{t, \sigma, x, \hat{x}} = f_2(t, \sigma, \hat{\sigma}, x, \hat{x})$$

haverik dua alderafuko
ditiymak
mendiklo tasumak
etapufuta

$$\left. \begin{array}{l} \bar{\lambda} = \bar{\lambda}(t, \sigma, \hat{\sigma}, x, \hat{x}) \\ \lambda = \lambda(t, \sigma, x) \\ \hat{\lambda} = \hat{\lambda}(t, \hat{\sigma}, \hat{x}) \end{array} \right\}$$

$$\frac{\lambda}{\bar{\lambda}} = \frac{\lambda(t, \sigma, x)}{\bar{\lambda}(t, \sigma, \hat{\sigma}, x, \hat{x})} = g_1(\sigma, \hat{\sigma})$$

$$\frac{\hat{\lambda}}{\bar{\lambda}} = \frac{\hat{\lambda}(t, \hat{\sigma}, \hat{x})}{\bar{\lambda}(t, \sigma, \hat{\sigma}, x, \hat{x})} = g_2(\sigma, \hat{\sigma})$$

$$\bar{\lambda}(t, \sigma, \hat{\sigma}, x, \hat{x}) \rightarrow \bar{\lambda}(t, \sigma, \hat{\sigma}, x) \text{ ①}$$

$$\begin{array}{l} \bar{\lambda}(t, \sigma, \hat{\sigma}, x) \rightarrow \bar{\lambda}(t, \sigma, \hat{\sigma}) \text{ ②} \\ \hat{\lambda}(t, \hat{\sigma}, \hat{x}) \rightarrow \hat{\lambda}(t, \hat{\sigma}) \text{ ③} \end{array}$$

alderafetawa ondurisa

$$\lambda(t, \sigma, x) \rightarrow \lambda(t, \sigma) \text{ ④}$$

$$\frac{\lambda}{\bar{\lambda}} = \frac{\lambda(t, \sigma)}{\bar{\lambda}(t, \sigma, \hat{\sigma})} = g_1(\sigma, \hat{\sigma})$$

$$\frac{\hat{\lambda}}{\bar{\lambda}} = \frac{\hat{\lambda}(t, \hat{\sigma})}{\bar{\lambda}(t, \sigma, \hat{\sigma})} = g_2(\sigma, \hat{\sigma})$$

$$\lambda(t, \sigma) = \phi(t) f_1(\sigma)$$

$$\bar{\lambda}(t, \sigma, \hat{\sigma}) = \phi(t) f_1(\sigma, \hat{\sigma})$$

$$\hat{\lambda}(t, \hat{\sigma}) = \phi(t) f_2(\hat{\sigma})$$

$$\bar{\lambda}(t, \sigma, \hat{\sigma}) = \phi(t) f_1(\sigma, \hat{\sigma})$$

regita...

(1)

$$\delta \bar{Q} = \delta Q + \delta \hat{Q}$$

$$\delta Q = \lambda d\sigma$$

adiatsioonipen ootkanna

$$\bar{\lambda} d\bar{\sigma} = \delta \bar{Q} = \lambda d\sigma + \hat{\lambda} d\hat{\sigma}$$

$$d\bar{\sigma} = \frac{\lambda}{\bar{\lambda}} d\sigma + \frac{\hat{\lambda}}{\bar{\lambda}} d\hat{\sigma}$$

$$\Rightarrow \bar{\sigma} = \bar{\sigma}(\sigma, \hat{\sigma}) \Rightarrow d\bar{\sigma} = \left(\frac{\partial \bar{\sigma}}{\partial \sigma}\right)_{\hat{\sigma}} d\sigma + \left(\frac{\partial \bar{\sigma}}{\partial \hat{\sigma}}\right)_{\sigma} d\hat{\sigma} \Rightarrow \left\{ \begin{array}{l} \left(\frac{\partial \bar{\sigma}}{\partial \sigma}\right)_{\hat{\sigma}} = \frac{\lambda}{\bar{\lambda}} \\ \left(\frac{\partial \bar{\sigma}}{\partial \hat{\sigma}}\right)_{\sigma} = \frac{\hat{\lambda}}{\bar{\lambda}} \end{array} \right\} = \left. \begin{array}{l} = g_1(\sigma, \hat{\sigma}) \\ = g_2(\sigma, \hat{\sigma}) \end{array} \right\}$$

(2)

$$\bar{\sigma} = \bar{\sigma}(t, \sigma, \hat{\sigma}, x, \hat{x})$$

$$d\bar{\sigma} = \left(\frac{\partial \bar{\sigma}}{\partial t}\right)_{\sigma, \hat{\sigma}, x, \hat{x}} dt + \left(\frac{\partial \bar{\sigma}}{\partial \sigma}\right)_{t, \hat{\sigma}, x, \hat{x}} d\sigma + \left(\frac{\partial \bar{\sigma}}{\partial \hat{\sigma}}\right)_{t, \sigma, x, \hat{x}} d\hat{\sigma} + \left(\frac{\partial \bar{\sigma}}{\partial x}\right)_{t, \sigma, \hat{\sigma}, \hat{x}} dx + \left(\frac{\partial \bar{\sigma}}{\partial \hat{x}}\right)_{t, \sigma, \hat{\sigma}, x} d\hat{x}$$

kõik hõlmab alderatku
ondurisa

$$\left(\frac{\partial \bar{\sigma}}{\partial t}\right)_{\sigma, \hat{\sigma}, x, \hat{x}} = \left(\frac{\partial \bar{\sigma}}{\partial x}\right)_{t, \sigma, \hat{\sigma}, \hat{x}} = \left(\frac{\partial \bar{\sigma}}{\partial \hat{x}}\right)_{t, \sigma, \hat{\sigma}, x} = 0$$

$$d\bar{\sigma} = \left(\frac{\partial \bar{\sigma}}{\partial \sigma}\right)_{t, \hat{\sigma}, x, \hat{x}} d\sigma + \left(\frac{\partial \bar{\sigma}}{\partial \hat{\sigma}}\right)_{t, \sigma, x, \hat{x}} d\hat{\sigma} \Rightarrow$$

$$\left(\frac{\partial \bar{\sigma}}{\partial \sigma}\right)_{t, \hat{\sigma}, x, \hat{x}} = f_1(t, \sigma, \hat{\sigma}, x, \hat{x}) ; \left(\frac{\partial \bar{\sigma}}{\partial \hat{\sigma}}\right)_{t, \sigma, x, \hat{x}} = f_2(t, \sigma, \hat{\sigma}, x, \hat{x})$$

hõlmab kaks alderatku
diferentsiaal
mõeldakse tasuvust
erututakse

$$\left. \begin{array}{l} \bar{\lambda} = \bar{\lambda}(t, \sigma, \hat{\sigma}, x, \hat{x}) \\ \lambda = \lambda(t, \sigma, x) \\ \hat{\lambda} = \hat{\lambda}(t, \hat{\sigma}, \hat{x}) \end{array} \right\}$$

$$\frac{\lambda}{\bar{\lambda}} = \frac{\lambda(t, \sigma, x)}{\bar{\lambda}(t, \sigma, \hat{\sigma}, x, \hat{x})} = g_1(\sigma, \hat{\sigma})$$

$$\frac{\hat{\lambda}}{\bar{\lambda}} = \frac{\hat{\lambda}(t, \hat{\sigma}, \hat{x})}{\bar{\lambda}(t, \sigma, \hat{\sigma}, x, \hat{x})} = g_2(\sigma, \hat{\sigma})$$

$$\bar{\lambda}(t, \sigma, \hat{\sigma}, x, \hat{x}) \rightarrow \bar{\lambda}(t, \sigma, \hat{\sigma}, x)$$

$$\lambda(t, \sigma, x) \rightarrow \lambda(t, \sigma)$$

normaalselt hõlmata jõuaks

$$\bar{\lambda}(t, \sigma, \hat{\sigma}, x) \rightarrow \bar{\lambda}(t, \sigma, \hat{\sigma})$$

$$\hat{\lambda}(t, \hat{\sigma}, \hat{x}) \rightarrow \hat{\lambda}(t, \hat{\sigma})$$

alderatkefunktsioon onduksioon

$$\left\{ \begin{array}{l} \lambda = \lambda(t, \sigma) \\ \hat{\lambda} = \hat{\lambda}(t, \hat{\sigma}) \\ \bar{\lambda} = \bar{\lambda}(t, \sigma, \hat{\sigma}) \end{array} \right\} \downarrow \text{regulaar...}$$

$$\frac{\lambda}{\bar{\lambda}} = \frac{\lambda(t, \sigma)}{\bar{\lambda}(t, \sigma, \hat{\sigma})} = g_1(\sigma, \hat{\sigma})$$

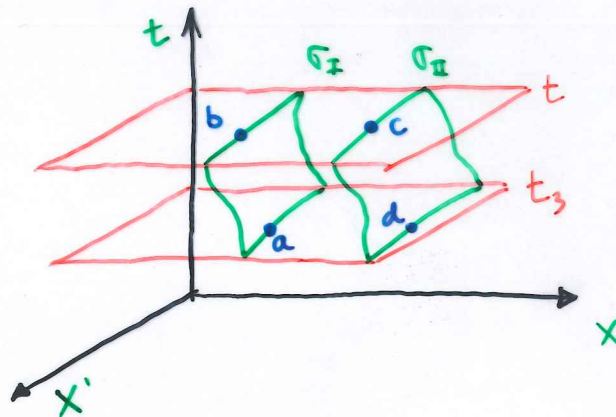
$$\frac{\hat{\lambda}}{\bar{\lambda}} = \frac{\hat{\lambda}(t, \hat{\sigma})}{\bar{\lambda}(t, \sigma, \hat{\sigma})} = g_2(\sigma, \hat{\sigma})$$

$$\begin{array}{l} \lambda(t, \sigma) = \phi(t) f_1(\sigma) \\ \bar{\lambda}(t, \sigma, \hat{\sigma}) = \phi(t) f(\sigma, \hat{\sigma}) \end{array}$$

$$\begin{array}{l} \hat{\lambda}(t, \hat{\sigma}) = \phi(t) f_2(\hat{\sigma}) \\ \bar{\lambda}(t, \sigma, \hat{\sigma}) = \phi(t) f(\sigma, \hat{\sigma}) \end{array}$$

(4) - KELVIN TEMPERATURA - ESKALA

SISTEMA $\{t, X, X'\}$ (SISTEMA EDOZEIN (ZAN DAITEKE))



$$Q = \phi(t) \int_{\sigma_I}^{\sigma_{II}} f(\sigma) d\sigma$$

$$\frac{Q}{Q_3} = \frac{\phi(t)}{\phi(t_3)} = \frac{Q \text{ TRANSFERITU DEN } t \text{ TEMPERATURAREN FUNTIOA}}{Q_3 \text{ TRANSFERITU DEN } t_3 \text{ TEMPERATURAREN FUNTIOA BERBERA}}$$

↓
EZ DAGO SISTEMA (SISTEMAREN ERANGARRIRIK) $\Rightarrow \phi(t) \propto T \Rightarrow$ TEMPERATURA ABSOLUTUA

$$\frac{Q(\{\sigma_I \rightarrow \sigma_{II}\}, T)}{Q_3(\{\sigma_I \rightarrow \sigma_{II}\}, T_3)} = \frac{T}{T_3}$$

$$T = 273.16 \left[\frac{Q}{Q_{PH}} \right] K$$

ZERO ABSOLUTUA... ?

KELVIN TEMPERATURA - ESKALA $\iff$ GAS IDEALAREN TEMPERATURA - ESKALA

↓ KELVIN TEMPERATURA
GAS-TERMOMETROA ERABILITZ NEURQU

(5) ENTROPIA FUNTzioAREN EXISTENTZIA

$$\delta Q = \lambda d\sigma$$

$$\lambda = \phi(t) f(\sigma)$$

$$\delta Q = \phi(t) f(\sigma) d\sigma$$

$$\frac{Q'}{Q} = \frac{T'}{T} \rightsquigarrow \frac{\delta Q'}{\delta Q} = \frac{T'}{T} \rightsquigarrow T = k \phi(t)$$

$$\frac{\delta Q}{T} = \frac{1}{k} f(\sigma) d\sigma$$

$$dS = \frac{\delta Q_{1g}}{T}$$

FISIKOKI ZER DEN
ZER EQIN BEHAR DEN

$$S_f - S_i = \int_i^f \frac{\delta Q_{1g}}{T}$$

$$\oint_{1g} \frac{\delta Q}{T} = 0$$

CLAUSIUS-EN TEOREMA

LABURBILDUMA

$$\delta Q = dU - \delta W$$

LEHENENGO PRINTZÍPIOA PROZESU IRULGARRIAN

$$(\delta Q)_{ig} = (dU - \delta W)_{ig}$$

ALDAGAI TERMODINAMIKOEN FUNTzioAN

$$\frac{(\delta Q)_{ig}}{T}$$

ZATIKETA

$$\int [ds = \frac{(\delta Q)_{ig}}{T}]$$

INTEGRATzioA

FORMULAZIOZ ALDATZEAN, METODOA BESTE BAT IZANGO DA.

ADIBIDEA : GAS IDEALARI DAGOKION ENTROPIA

$$dS = \frac{\delta Q_{ig}}{dT}$$

$$(i) (a) \Delta S = \int \frac{\delta Q_{ig}}{T} = \int \frac{1}{T} [C_p dT - V dp] = \int \frac{C_p}{T} dT - \int \frac{V}{T} dp$$

$$\Delta S \equiv S - S_r = C_p \ln \frac{T}{T_r} - nR \ln \frac{P}{P_r}$$

$$S = C_p \ln T - nR \ln P + \{S_r - C_p \ln T_r + nR \ln P_r\}$$

$$S = C_p \ln T - nR \ln P + S_0$$

$$(b) dS = \frac{1}{T} C_p dT - \frac{1}{P} nR dp \leadsto$$

$$S = \int \frac{C_p}{T} dT - nR \ln P + S_0$$

$$(ii) (a) \Delta S = \int \frac{\delta Q_{ig}}{T} = \int \frac{1}{T} [C_v dT + P dV] = \int \frac{C_v}{T} dT + \int \frac{P}{T} dV$$

$$\Delta S \equiv S - S_r = C_v \ln \frac{T}{T_r} + nR \ln \frac{V}{V_r}$$

$$S = C_v \ln T + nR \ln V + \{S_r + C_v \ln T_r + nR \ln V_r\}$$

$$S = C_v \ln T + nR \ln V + S_0$$

$$(b) dS = \frac{1}{T} C_v dT + \frac{1}{V} nR dV \leadsto$$

$$S = \int \frac{C_v}{T} dT + nR \ln V + S_0$$

$$\left. \begin{aligned} dS &= \frac{\delta Q_{16}}{T} \\ \delta Q_{16} &= dU - \delta W \end{aligned} \right\} dS = \frac{dU - \delta W}{T}$$

aniketa $\rightarrow$

- aldagaiak (T, p) ; (T, V) ; (p, V) sistema hidentafikazaren kasuan, itxia (2 arkatasmu-gradu)
 (T, X) ; (T, Y) ; (Y, X) beste edozein sistemaren kasuan (2 arkatasmu-gradu)

- materia haurerako } aldagai independenteen sata aukeratu
 amaietarako }

- sistema berrak informazioa:

- egoera-erakusketak : - termikoa
 - mekanikoa (besten)

- koefiziente esperimentalak :- $(C_p, C_v, \alpha, \kappa_T)$

- denak eta dira independenteak : $C_p - C_v = \frac{TV\alpha^2}{\kappa_T}$

- (T, V)	$\delta Q = C_v dT + \frac{C_p - C_v}{V\alpha} dV$	$\Rightarrow dS = \frac{\delta Q}{T} = \frac{C_v}{T} dT + \frac{C_p - C_v}{TV\alpha} dV$	$\Rightarrow S = S(T, V) \Rightarrow \begin{cases} \left(\frac{\partial S}{\partial T}\right)_V = \frac{C_v}{T} \\ \left(\frac{\partial S}{\partial V}\right)_T = \frac{C_p - C_v}{TV\alpha} \end{cases}$
- (p, V)	$\delta Q = \frac{C_p}{V\alpha} dV + \frac{\kappa_T}{\alpha} C_v dp$	$\Rightarrow dS = \frac{\delta Q}{T} = \frac{C_p}{TV\alpha} dV + \frac{\kappa_T}{\alpha} \frac{C_v}{T} dp$	$\Rightarrow S = S(V, p) \Rightarrow \begin{cases} \left(\frac{\partial S}{\partial V}\right)_p = \frac{C_p}{TV\alpha} \\ \left(\frac{\partial S}{\partial p}\right)_V = \frac{\kappa_T C_v}{\alpha T} \end{cases}$
- (p, T)	$\delta Q = C_p dT + \frac{\kappa_T}{\alpha} (C_v - C_p) dp$	$\Rightarrow dS = \frac{\delta Q}{T} = \frac{C_p}{T} dT + \frac{\kappa_T}{T\alpha} (C_v - C_p) dp$	$\Rightarrow S = S(T, p) \Rightarrow \begin{cases} \left(\frac{\partial S}{\partial T}\right)_p = \frac{C_p}{T} \\ \left(\frac{\partial S}{\partial p}\right)_T = \frac{\kappa_T}{\alpha T} (C_v - C_p) \end{cases}$

* Gaurko ikolatu emari behar du

* atzeratzea

$$\delta Q = dU - \delta W$$

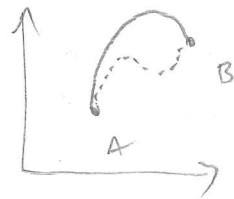
Lehenengo printzipioaren adierazpen hori prozesu itzulgarria da

$$(\delta Q)_{12} = \left(\frac{\delta Q}{T} \right)_{12} \rightarrow \text{aldeari termodinamika menpe}$$

$$\frac{\delta Q_{12}}{T} \rightarrow \text{temperatura erabakitze gaitasuna}$$

$$\left(\frac{\delta Q_{12}}{T} \right) \rightarrow \text{integratze berriz}$$

* erabakitze prozesuak dS baina kontatu modua: prozesu itzulgarria zehar



ΔS_{AB} funtzioa

ΔS_{AB} kontaketa = prozesu itzulgarria erabakitze indertkatu konstante baten bidez

$$dS = \frac{\delta Q_{12}}{T}$$

$$\frac{\delta Q}{T} = ? \text{ baina etda } dS$$

Itzulgarria $dS = \frac{\delta Q_{12}}{T} \Rightarrow dS = 0 \Rightarrow S = kT$

adibetarikoa $\delta Q_{12} = 0$

$$C_v = T \left(\frac{\partial S}{\partial T} \right)_V \rightarrow \text{Lehenengo printzipioa abiatu} \delta Q = dU - \delta W$$

$$C_p = T \left(\frac{\partial S}{\partial T} \right)_P$$

$$T dS = dU - \delta W$$

$$dS = \frac{1}{T} [dU - \delta W] =$$

$$dS = \frac{1}{T} [dU - Y dX]$$

$$S = S(T, V) \Rightarrow \left[dS = \left(\frac{\partial S}{\partial T} \right)_V dT + \left(\frac{\partial S}{\partial V} \right)_T dV \right] T \Big|_P$$

$$S = S(T, P) \Rightarrow$$

Lehenengo printzipioa modura eta
erabakitze-modura adierazteko: prozesu itzulgarria erabakitze

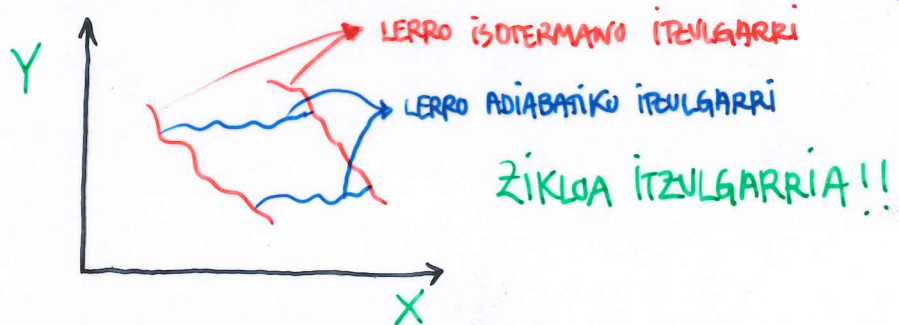
METODO TEKNIKOA

* CARNOT-EN ZIKLOA:

BI LERRO ISOTERMANO ITZULGARRIZ
BI LERRO ADIABATIKO ITZULGARRIZ } OSATURIKO ZIKLOA
EDOZEIN SISTEMAREN KASUAN

$$S = S(Y, X)$$

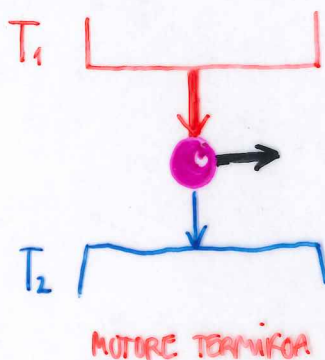
SISTEMA



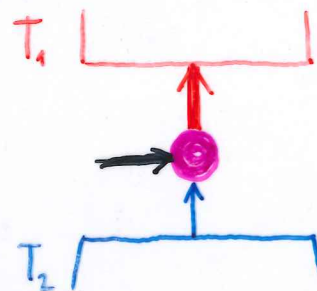
DEFINIZIOAREN ONDORIOZ:

ZURGATUTAKO BEROA, GOI-TENPERATURAN DAGEN BERO-ITURRITIK
KANPORANTAKO BEROA, BEHE-TENPERATURAN DAGEN BERO-ITURRIRA }
BI BERO-ITURRI BAINO EZ DAGO

* CARNOT-EN MOTOREA ETA HOZKAILUA



MOTORE TERMIKOA



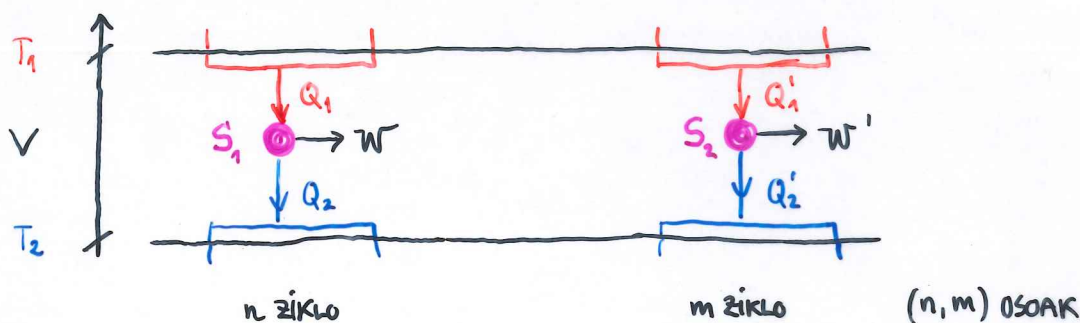
HOZKAILUA

* CARNOT-EN ZIKLOAREN ADIERAZPIDE GRAFIKOA T/S DIAGRAMAN

+ ETEKINAREN ADIERAZPENEA

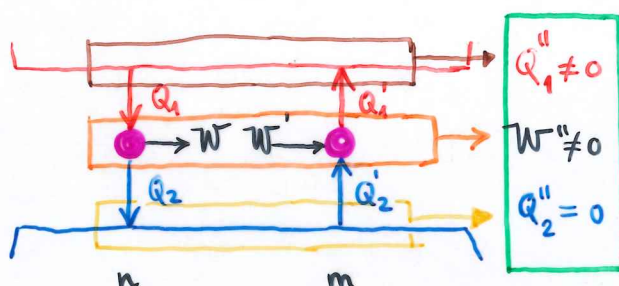
(1) - CARNOT-EN MOTOREAREN ETEKINAK EZ DAUKA SISTEMAREKIKO MENPEKOTASUNIK

$\left[\left(-\frac{Q_2}{Q_1} \right) \right]$ ADIERAZPENAK BALIO KONSTANTEA DAUKA (T_1, T_2) BIKOTEA FINKATUZ GERO



$$n|Q_2| = m|Q'_2| \quad \left\{ nQ_2 + mQ'_2 = 0 \right\} \quad \text{HAUXE DA EGİN DUGUN AUKERA}$$

- MHIIZTATUKO DITUGU, (n, m) ZIKLO BAKARRA, KONTRAKO ZEINUAREKIN



ZIKLO BAKAR OSOARI LEHENENGU PRINTZIPIOA APLIKATUKO DUGU:

$$nQ_1 + mQ'_1 = \Delta U - W'' \quad \Delta U = 0 \text{ ZIKLOA BAITA}$$

$$nQ_1 + mQ'_1 = -W''$$

$$nQ_1 + mQ'_1 > 0 \quad \text{EZINEZKOA !!} \quad 2. \text{PRINTZIPIOAREN AURKA}$$

$$nQ_1 + mQ'_1 \leq 0$$

ZIKLOA ALDERANETUZ GERO: ITZULGARRIA BAITA ...

$$nQ_1 + mQ'_1 \geq 0$$

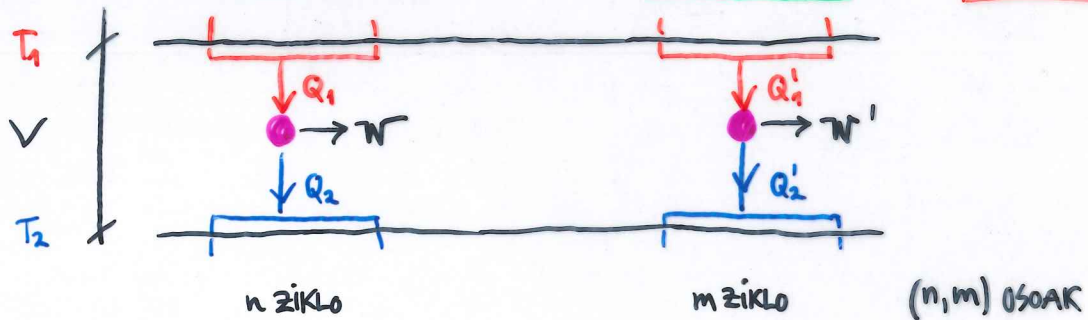
$$nQ_1 + mQ'_1 = 0$$

$$nQ_2 + mQ'_2 = 0 \text{ HIPOTESIS}$$

$$\frac{Q_2}{Q_1} = \frac{Q'_2}{Q'_1}$$

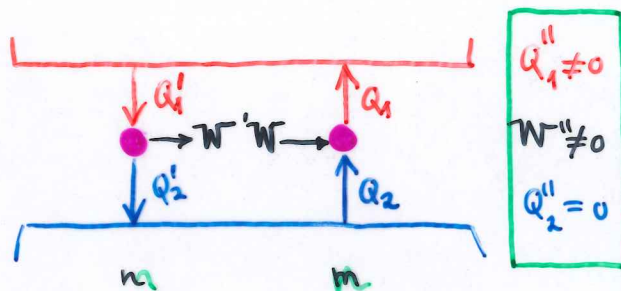
(2) - CARNOT-EN MOTOREAK FINKATURIKO TEMPERATUREN ARTEKO ETEKIN MAXIMOA

$$\eta = \frac{|W|}{|Q_1|} = \frac{|Q_1| - |Q_2|}{|Q_1|} \Rightarrow \boxed{\eta_C = 1 - \frac{|Q_2|}{|Q_1|}} > \boxed{\eta^* = 1 - \frac{|Q_2'|}{|Q_1'|}} \Rightarrow \boxed{\frac{|Q_2|}{|Q_1|} \leq \frac{|Q_2'|}{|Q_1'|}}$$



$$n |Q_2| = m |Q_2'| \quad \left\{ n Q_2 + m Q_2' = 0 \right\} \quad \text{HAUKE DA EGIN DUGUN AUKERA}$$

- MITIIZTATUKO DITUQU, (n, m) ZIKLO BAKARRA, CARNOT-EN MOTOREARI BUELTA



ZIKLO BAKAR OSOARI LEHENENGO PRINTZÍPIOA APLIKATUKO DITUQU:

$$n Q_1 + m Q_1' = \Delta U - W'' \quad \Delta U = 0 \text{ ZIKLOA BAITA}$$

$$n_1 Q_1 + m Q_1' = -W''$$

$$n_1 Q_1 + m Q_1' > 0$$

EZINEZKOA !! 2. PRINTZÍPIOAREN KO.

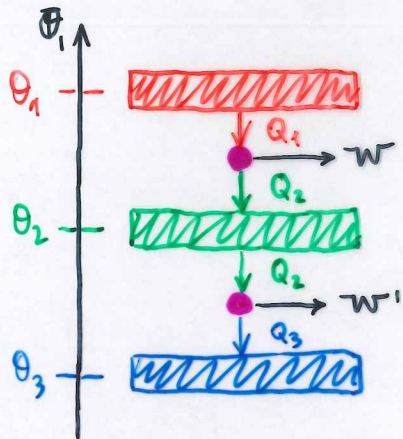
$$\boxed{n_1 Q_1 + m Q_1' \leq 0}$$

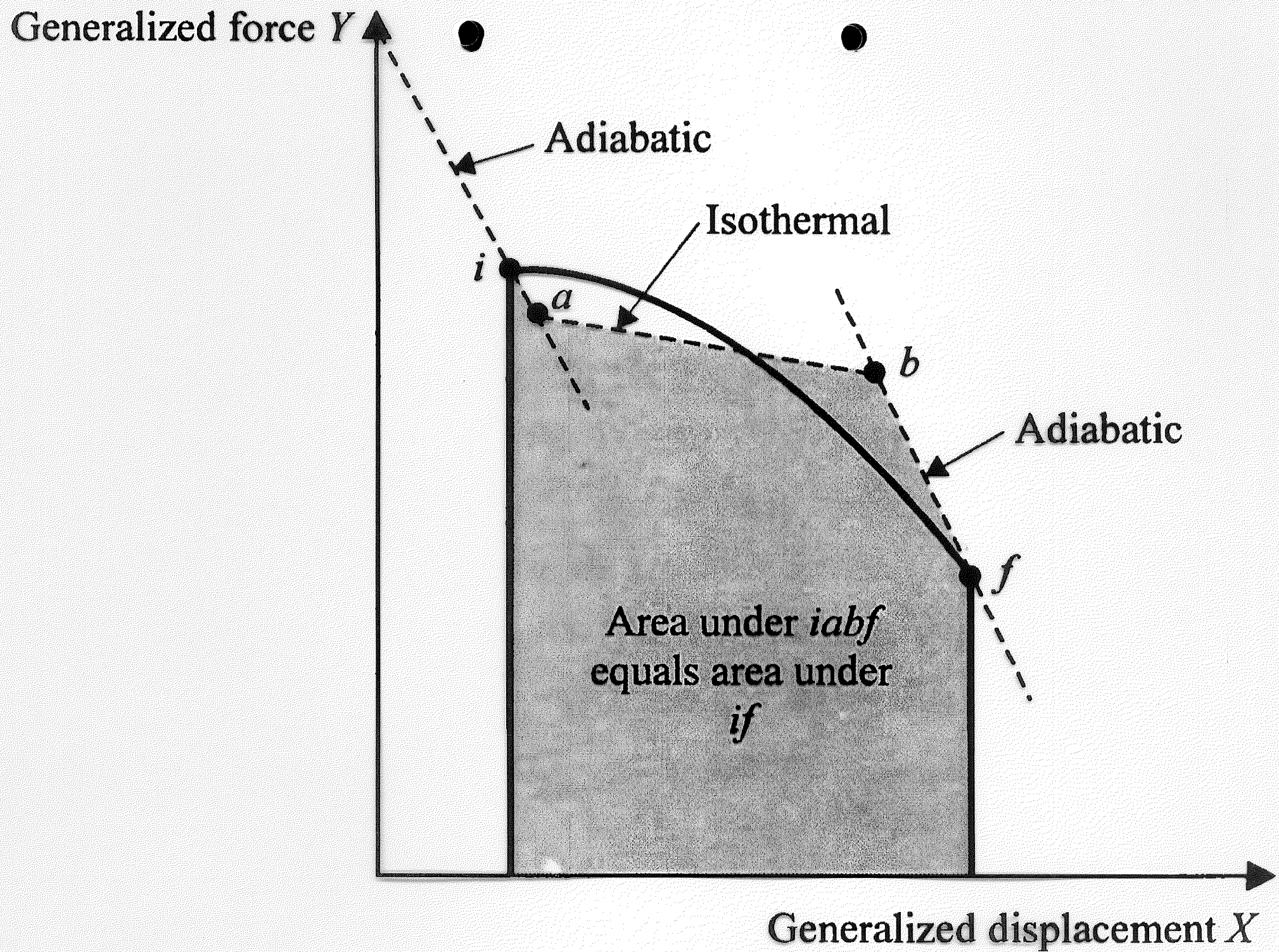
$$\left. \begin{aligned} -n |Q_2'| &= -m |Q_2| \Rightarrow n |Q_2'| = m |Q_2| \\ n |Q_1'| &\leq m |Q_1| \Rightarrow n |Q_1'| \leq m |Q_1| \end{aligned} \right\} \boxed{\frac{|Q_2|}{|Q_1|} \leq \frac{|Q_2'|}{|Q_1'|}}$$

(= CARNOT-EN KASUA)

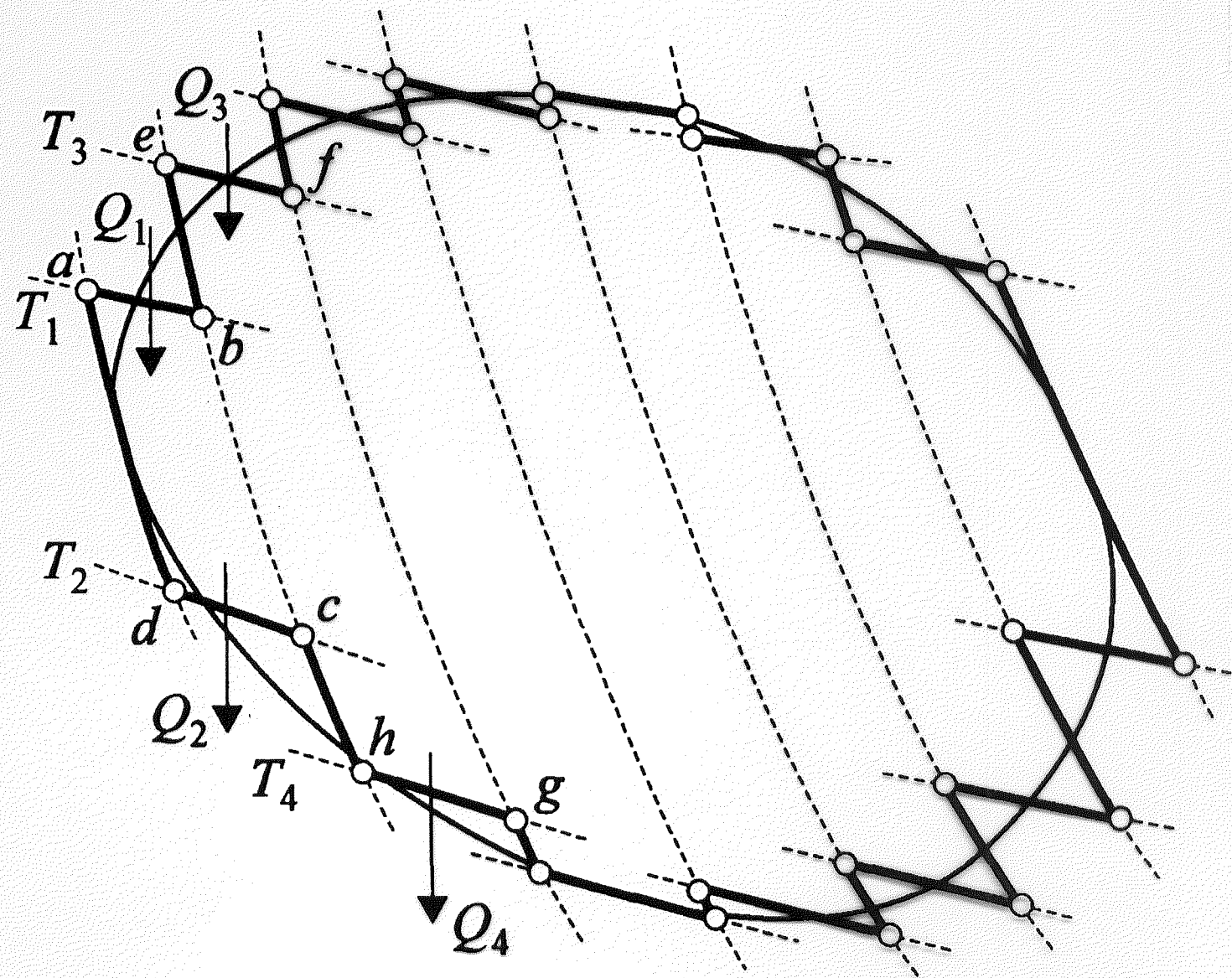
KELVIN TEMPERATURA-ESKALA

$$\left[\frac{Q_2}{Q_1} = f(\theta_2, \theta_1) = \phi(\theta_2) \phi(\theta_1) = \frac{\psi(\theta_2)}{\psi(\theta_1)} \left\{ \begin{array}{l} \text{BANATUTA} \\ \text{UNIBERTSALA} \end{array} \right\} \right]$$





Generalized
force Y



Generalized displacement X

CLAUSIUS-EN TEOREMA

- * PROZESU [] HONETAN SISTEMA ETA INGURUNEAREN ARTEKO BERO-TRUKAKETAK POSITIBOAK ZEIN NEGATIBOAK IZAN DAITEZKEENAK

SISTEMA T_i TEMPERATURAN DAGOENEAN Q_i BEROA TRUKATUKO DU (ZURGATU/KANPORATU)

- * BERO-TRUKAKETAK CARNOT-EN MOTOREEN BIDEZ ADIERAZIKO DITUGU ONDOKO EREDUARI SEGITUZ

T_0 ARBITRARIOKI FINKATURIKO BERO-ITURRIAREN TEMPERATURA

Q_j TRUKATUKO DEN BERO-KANTITATEA

BESTE BERO-ITURRIAREN TEMPERATURA T_j DA ; Q_j BEROA TRUKATU AHAL IZATEKO

$$\left\{ \begin{array}{l} \{Q_j\} \quad j=1, \dots, n \\ \downarrow \\ T_j \end{array} ; T_0 \right\} \quad \boxed{[T_j, T_0] \quad j=1, \dots, n}$$

CARNOT-EN MOTOREA/HOTZKAILUA

- * T_j EZ DA ZIKLOKI ARITUKO DEN SISTEMA TARTEKARIAREN TEMPERATURA (PRINTZIBIOZ, NAHIZ ETA ZIKLO ITZULGARRIAREN KASUAN BAI)

BAIZIK ETA TRUKATUKO DEN Q_j TRUKATZEKO BEHAR DENA

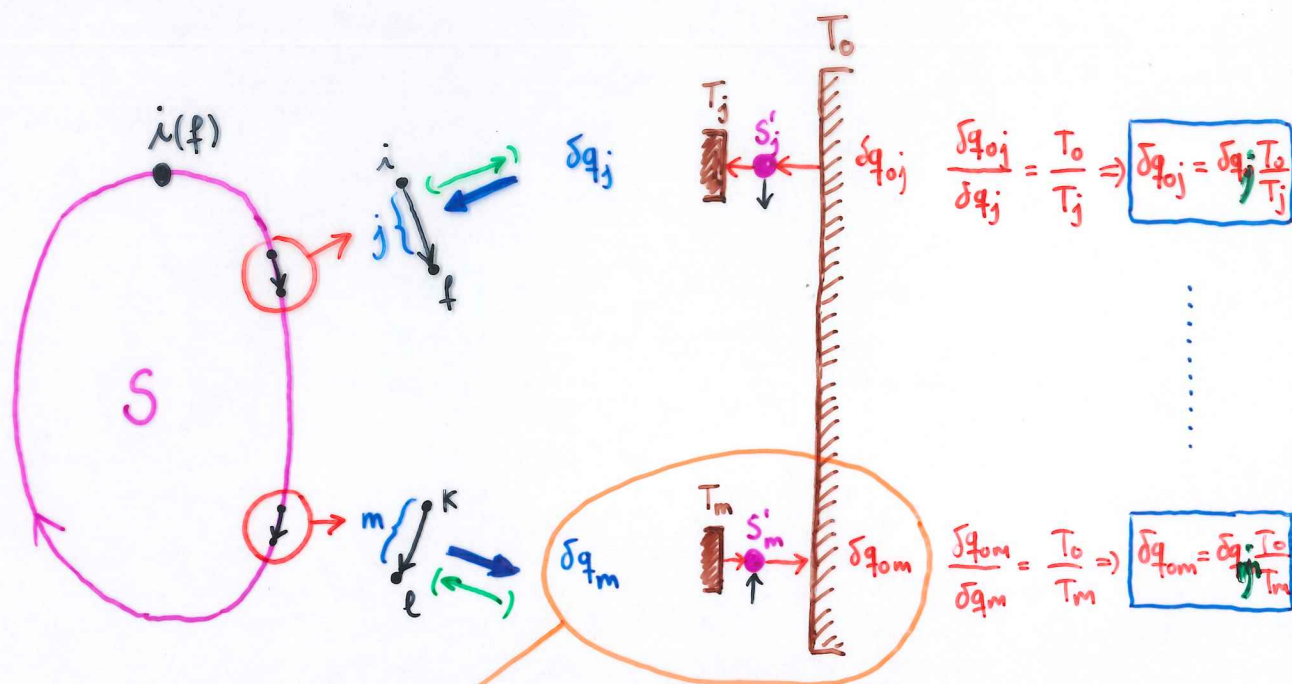
T_0 ALDATUZ GERO T_j -REN BALIOA DIFERENTE DA (NAHIZ ETA Q_j ALDATU EZ)

$$\boxed{Q_j = Q_0 \frac{T_j}{T_0}} ; T_0 \rightarrow T'_0 \Rightarrow \boxed{Q_j = Q'_0 \frac{T_j}{T'_0}}$$

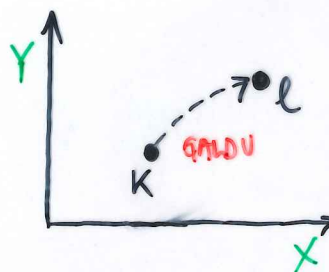
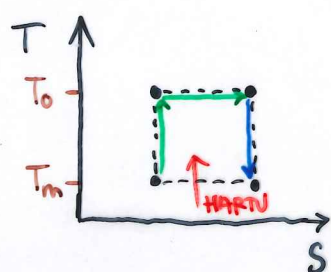
T_j SISTEMA BITARTEKARIAREN TEMPERATURA

ZIKLO OSOA ITZULGARRIA BADA

ZIKLOKI ARITUKO DEN SISTEMARENA ERE , OREKA BEHAR BAITUGU (BESTELA ITZULEZINTASUNAK AGERTUKO DIRA)

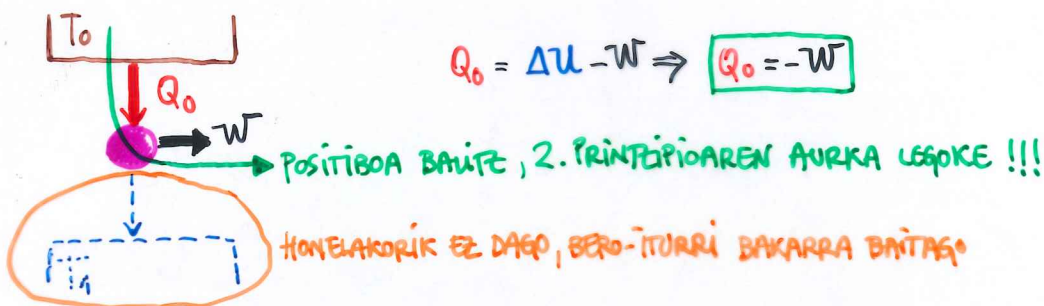


$$\int \delta q_0 = T_0 \int \frac{\delta q}{T}$$



$$\int \delta q_0 = T_0 \int \frac{\delta q}{T}$$

BERO-ITURRIAREN KIN SISTEMAK TRUKATU DUEN BERO-KANTITATEA, EFEKTIBOA



$$Q_0 = \Delta U - W \Rightarrow Q_0 = -W$$

$$T_0 \int \frac{\delta q}{T} \leq 0$$

$$\int \frac{\delta q}{T} \leq 0 \quad *$$

ITZULGARRIA DENEZ; BUELTA EMAN DIBZATIOKEGU!!

$$\int \frac{\delta q}{T} = 0 \quad \text{ZIKLO ITZULGARRIA}$$

$$\int \frac{\delta q}{T} < 0 \quad \text{ZIKLO ITZULETZA}$$

CLAUSIUS-EN TEOREMA

↓ S ENTROPIA FUNTzioAREN EXISTENTZIA FROSA DAITEKE (ariketa)

* $\int \frac{\delta q}{T}$ EZ DA ENTROPIA KONTUZ!!!

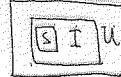
* Entropia berrakoa
iruntzia

$$* G_{p,v} = T \left(\frac{\partial S}{\partial T} \right)_{p,v}$$

* T/S diagraman
T=kTe, S=kTe, V=kTe, P=kTe

ENTROPIA-EMENDIOAREN PRINTZIPIOA

Prozesuaren zehazteko entropia-aldakuntza (Hasierako eta amaierako egoerak $\rightarrow$ orka-egoerak)



Ez-Adiabatikoa

Hulgamiak		Hulerinak					Adiabatikoa
B-I bakarra	B-I-en sorta	Kanpoko (Hulerintasun mekanikoa)		barneko (Hulerintasun mekanikoa)	Kanpoko (Hulerintasun termikoa)	Kanpoko (Hulerintasun kimikoa)	Hulerinak
		W isatermiko ΔU_{B-I} $\rightarrow W \left[\Delta U \right]$	W adiabatikoa ΔU_S 	$\Delta U \rightarrow$ energia mekanikoa $\rightarrow \Delta U$ "expansio aska" 			
			(i) $p = kT$ (ii) $V = kT$ 				
		$\Delta S_{in} = \frac{W}{T}$	$\Delta S_{in} = 0$	$\Delta S_{in} = 0$	$\Delta S_{in} = \frac{Q}{T_2} - \frac{Q}{T_1}$	$\Delta S_{in} = 0$	
		$\Delta S_s = 0$	$\Delta S_s = \left\{ \begin{array}{l} C_p \ln \frac{T_f}{T_i} \\ C_v \ln \frac{T_f}{T_i} \end{array} \right.$	$\Delta S_s = R \ln 2$ *	$\Delta S_s = 0$	$\Delta S_{s(1,2)} = 2 R \ln 2$ *	
		$\Delta S_o = \frac{W}{T} > 0$	$\Delta S_o = \left\{ \begin{array}{l} C_p \ln \frac{T_f}{T_i} \\ C_v \ln \frac{T_f}{T_i} \end{array} \right. > 0$	$\Delta S_o = R \ln 2 > 0$	$\Delta S_o = \frac{Q}{T_2} - \frac{Q}{T_1} > 0$	$\Delta S_o = 2 R \ln 2 > 0$	
K O N P R O B A T U							Frogatu

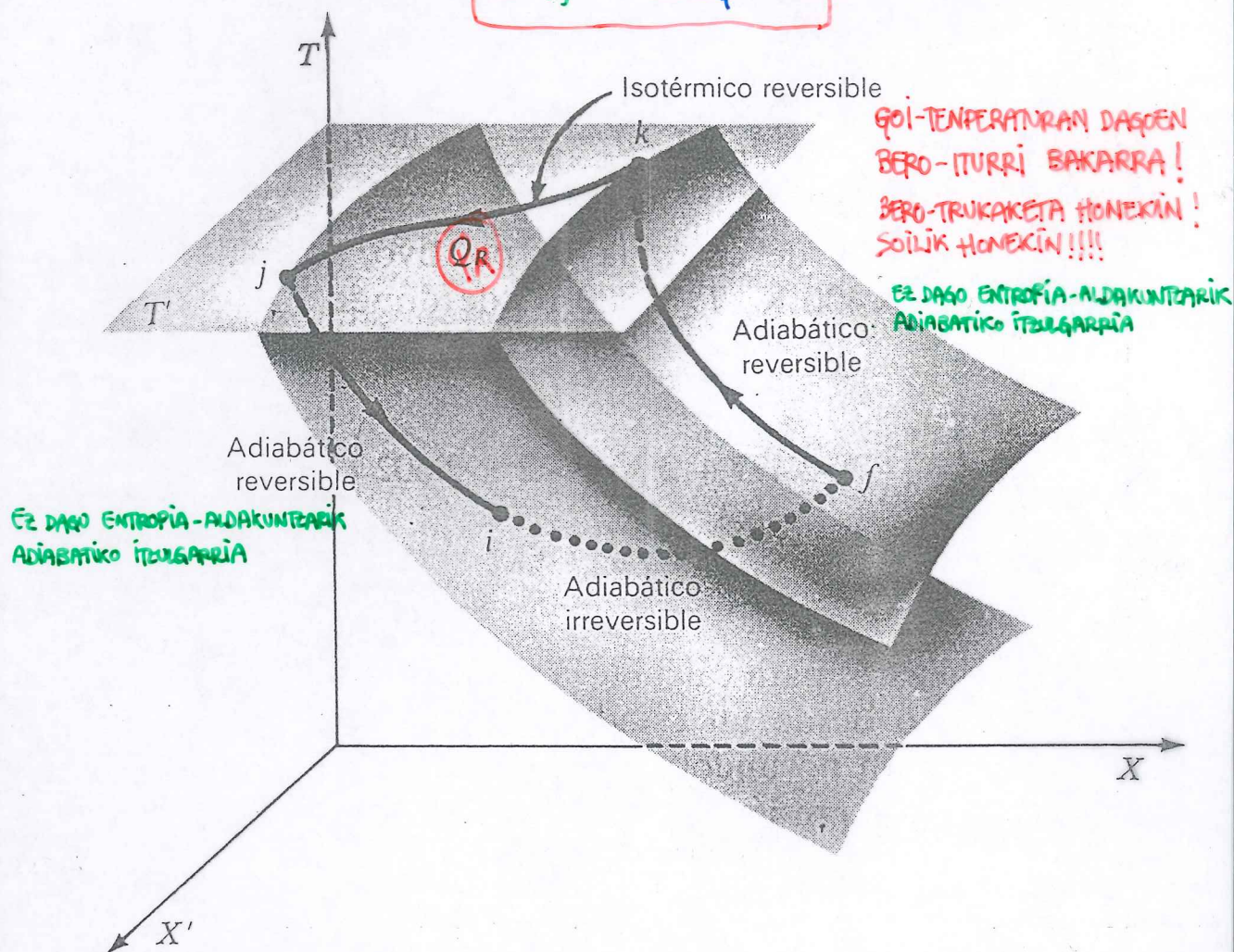
$$\Delta S_{tot} > 0$$

guztiz isolatuak dauden sistemari dagotio

SISTEMA

$$\left[\Delta S_o = \Delta S_{kj} + \underset{0}{\Delta S_{ji}} + \Delta S_{if} + \underset{0}{\Delta S_{fk}} = 0 \text{ (ZIKLOA)} \right]$$

$$\Delta S_{kj} + \Delta S_{if} = 0$$



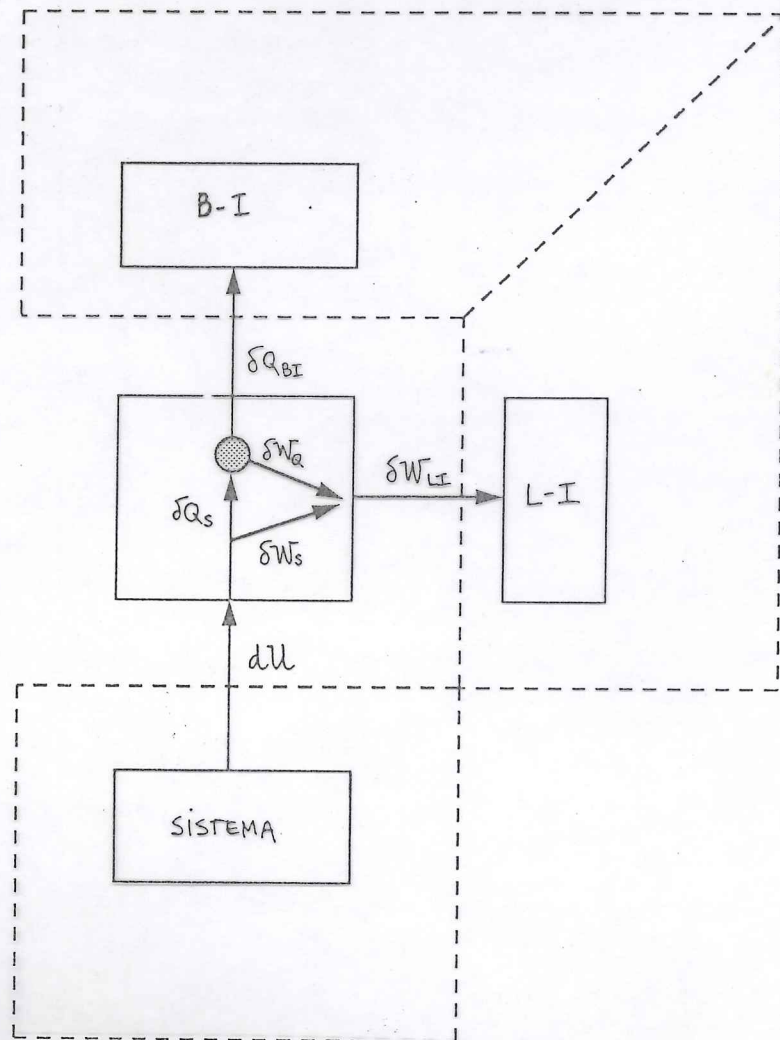
$$\left. \begin{array}{l} \Delta S_{kj} \equiv S_j - S_k \\ \Delta S_{if} \equiv S_f - S_i \end{array} \right\} \Delta S_{if} + \Delta S_{kj} = 0 \Rightarrow \Delta S_{if} = -\Delta S_{kj} \Rightarrow \Delta S_{if} = \Delta S_{jk} = S_k - S_j$$

$$Q_R = T' \Delta S_{kj}$$

$$Q_R \leq 0 \text{ (2.P)} \Rightarrow \Delta S_{kj} \leq 0 \Rightarrow \Delta S_{jk} \geq 0$$

$$\Delta S_{if} \geq 0$$

LAN MAXIMOA



KUALITATIBOKI

ΔU_s } SISTEMARI DAGOKION BI ALDAKUNTZA HAUEN
 ΔS_s } FINKOAK DIRA, OREKA-ESPERAK FINKOAK

$$(-\Delta U_s) = Q_{BI} + W_{LI} \quad \text{EKP}$$

MAXIMIZATU

MINIMIZATU

$$\Delta S_o = \Delta S_s + \Delta S_{BI} \rightarrow \text{MINIMIZATU}$$

FINKO

MINIMIZATU !!

HAR DEBAKEEN BAIORIK TXIKIENA
 BERDINTA DUGUNEAN DA, BEZAK
PROZESU ITZULGARRIA BURUTUZ

$$Q = \Delta U' - W$$

$$\Delta U' = U_B - U_A$$

$$Q + W - \Delta U' = 0$$

$$\Delta U = -\Delta U'$$

$$Q + W + \Delta U = 0$$

$$Q_{bfi} + W_{efi} + \Delta U_s = 0$$

$$Q_{bfi} + W_{efi} + (U_A - U_B) = 0$$

W_{efi} maksimum $\Rightarrow Q_{bfi}$ minimum $\Rightarrow \Delta S_{bfi}$ minimum $\Rightarrow \Delta S_{osoa}$ minimum $\Rightarrow$

ΔS_{osoa} minimum $\Rightarrow$ "Minimumum baxsema"
"Minimuma absolutna"

$$\Delta S_{osoa} = 0 \quad \text{PROZESI ITULGARMA}$$

$$dU + \delta Q_{bfi} + \delta W_{efi} = 0$$

EKP

$$dS_{osoa} = dS + \frac{\delta Q_{bfi}}{T_{bfi}} (\geq 0) \quad \begin{cases} > 0 & \text{IE} \\ = 0 & \text{IQ} \end{cases}$$

EEM

$$\delta W_{efi} = -dU - \delta Q_{bfi}$$

$$dS + \frac{\delta Q_{bfi}}{T_{bfi}} \geq 0 \Rightarrow \frac{\delta Q_{bfi}}{T_{bfi}} \geq -dS \Rightarrow -\delta Q_{bfi} \leq T_{bfi} dS$$

$$\Rightarrow \delta W_{efi} \leq -dU + T_{bfi} dS$$

$$\delta Q = dU - \delta W \Rightarrow -dU = -\delta Q - \delta W$$

$$\delta W_{efi} \leq -\delta Q - \delta W + T_{bfi} dS$$

$$[\delta W_{efi}]_M = -\delta Q - \delta W + T_{bfi} dS$$

maximuma berdinlan betle denlan
berdinlan bada $\Rightarrow$ prozessi itulgarma

$$\delta Q = T dS$$

$$[\delta W_{efi}]_M = -T dS - \delta W + T_{bfi} dS$$

$$= -T dS \left(1 - \frac{T_{bfi}}{T}\right) - \delta W$$

$$[\delta W_{efi}]_M = \left(1 - \frac{T_{bfi}}{T}\right)(-\delta Q) + (-\delta W)$$

$(-\delta W)$ zuzenlan atavatako lana

$(-\delta Q)$ zuzenlan atavatako baxsema
fraksiya

$$Q = \Delta U - W$$

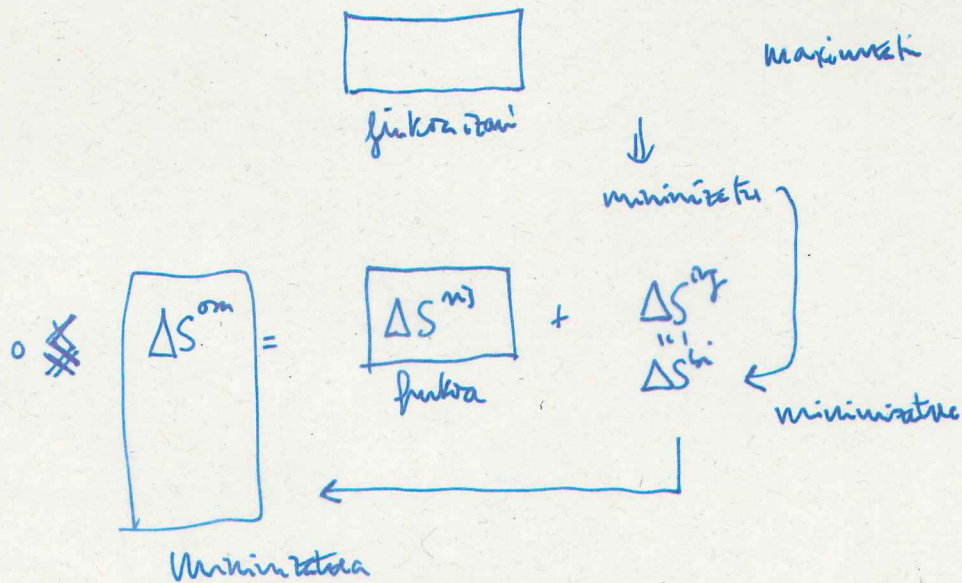
$$(Q = \Delta u - W)^{in} \Rightarrow (-\Delta u)^{in} = -(Q + W)^{in}$$

$$= -Q^{in} - W^{in}$$

$$= Q^{out} + W^{out}$$

$$(-\Delta u)^m = Q^i + W^i \quad 1P \quad (EKP)$$

1 P (EKP)



$$\begin{aligned} \delta Q &= dU - \delta W \\ (\delta Q = dU - \delta W)^{in} \\ (-dU)^{in} &= -(\delta Q + \delta W) \\ -dU^{in} &= \delta Q^{in} + \delta W^{in} \\ 0 &= dU + \delta Q^{in} + \delta W^{in} \end{aligned}$$

$$\delta W^{hi} = -dU - \delta Q^{hi}$$

$$dS + \frac{\delta Q_{hi}}{T_{hi}} \geq 0$$

$$\frac{\delta Q^{in}}{T^{in}} \geq -dS$$

$$-\frac{\delta Q_{\text{rev}}}{T_{\text{rev}}} \leq dS$$

$$- \delta \phi^i \leq T^i dS$$

$$\begin{aligned}\delta Q &= dU - \delta W \\ dU &= \delta Q + \delta W \\ -dU &= -\delta Q - \delta W\end{aligned}$$

$$\delta W^{li} \leq -dU + T^{li} dS$$

$$\begin{aligned} \delta W^{hi} &\leq -\delta Q - \delta W + T^{hi} dS \\ \delta W^{hi} &= -T dS - \delta W + T^{hi} dS \end{aligned}$$

$$\delta W^{li} = -\delta W - T ds \left(1 - \frac{T^i}{T} \right)$$

$$Q = \Delta U' - W$$

$$\Delta U' = U_B - U_A$$

$$Q + W - \Delta U' = 0$$

$$\Delta U = -\Delta U'$$

$$Q + W + \Delta U = 0$$

$$Q_{\text{api}} + W_{\text{api}} + \Delta U_s = 0$$

$$Q_{\text{api}} + W_{\text{api}} + (U_A - U_B) = 0$$

W_{api} maksimisasi $\Rightarrow$ Q_{api} minimisasi $\Rightarrow \Delta S_{\text{api}}$ minimisasi $\Rightarrow \Delta S_{\text{sem}}$ minimisasi $\Rightarrow$
 ΔS_{sem} minimisasi $\Rightarrow$ "Minimumk bayuana"
 Minimum, absolutus

$$\Delta S_{\text{sem}} = 0 \quad \text{PROSES ITULUAKARIA}$$

$$dU + \delta Q_{\text{api}} + \delta W_{\text{api}} = 0$$

EKP

$$dS_{\text{sem}} = dS + \frac{\delta Q_{\text{api}}}{T_{\text{api}}} (\geq 0) \begin{cases} > 0 & \text{IE} \\ = 0 & \text{IG} \end{cases}$$

EEM

$$\delta W_{\text{api}} = -dU - \delta Q_{\text{api}}$$

$$dS + \frac{\delta Q_{\text{api}}}{T_{\text{api}}} \geq 0 \Rightarrow \frac{\delta Q_{\text{api}}}{T_{\text{api}}} \geq -dS \Rightarrow -\delta Q_{\text{api}} \leq T_{\text{api}} dS$$

$$\delta W_{\text{api}} \leq -dU + T_{\text{api}} dS$$

$$\delta Q = dU - \delta W \Rightarrow -dU = -\delta Q - \delta W$$

$$\delta W_{\text{api}} \leq -\delta Q - \delta W + T_{\text{api}} dS$$

$$[\delta W_{\text{api}}]_M = -\delta Q - \delta W + T_{\text{api}} dS$$

maksimum berdimensi beta deselan
 berdimensi beta $\Rightarrow$ prosesnya itulugama

$$\delta Q = T dS$$

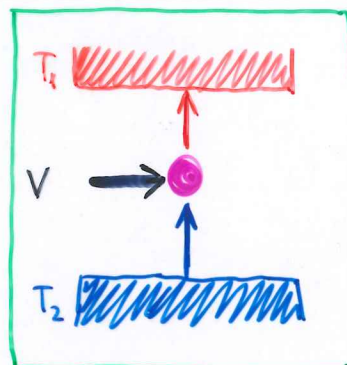
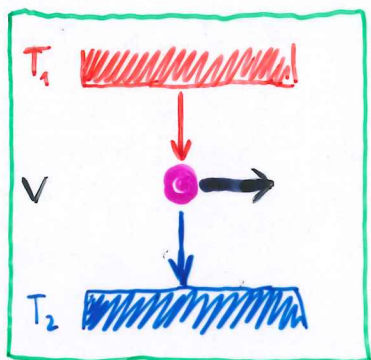
$$[\delta W_{\text{api}}]_M = -T dS - \delta W + T_{\text{api}} dS$$

$$= -T dS \left(1 - \frac{T_{\text{api}}}{T}\right) - \delta W$$

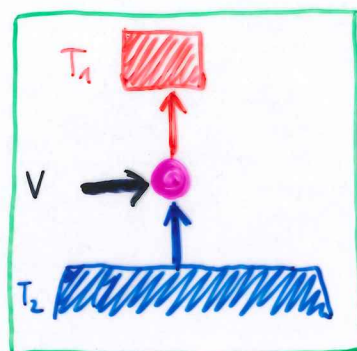
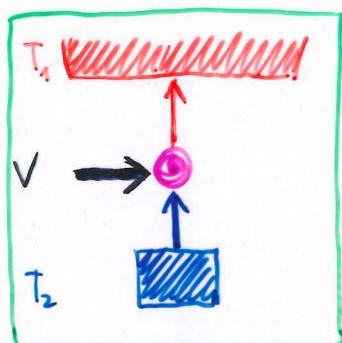
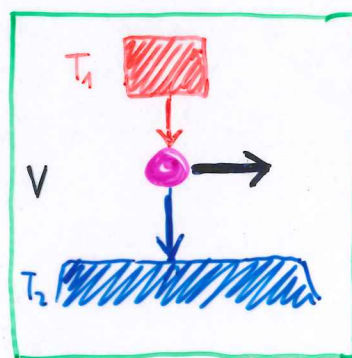
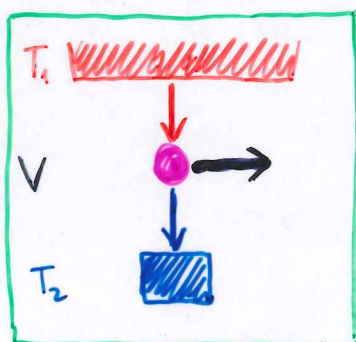
$$[\delta W_{\text{api}}]_M = \left(1 - \frac{T_{\text{api}}}{T}\right) (-\delta Q) + (-\delta W)$$

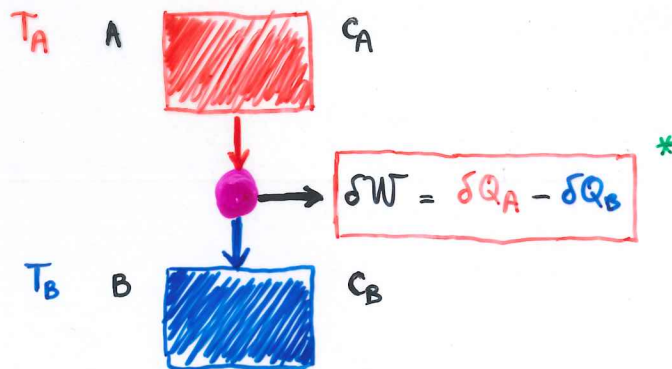
$(-\delta W)$ zureman atematako lava
 $(-\delta Q)$ zureman atematako berawon
 fra Kiora

LAN MAXIMOAREKIN LOTURIKO ZENBAIT ADIBIDE : "PROBLEMA-MOTAK"



SISTEMAREN (BERO-ITURRIA EZ DENAREN) BERO-AHALMENA JAKINA DA : C , C_v , C_p
SISTEMAREN TEMPERATURA ALDATUZ JOANGO DA !!!!





$$\delta W = \delta Q_1 - \delta Q_2$$

$$\int \delta W = \int \delta Q_1 - \int \delta Q_2 \Rightarrow \boxed{W = Q_1 - Q_2} \quad \text{HAUXE DA KALKULATU BEHARRERKOA}$$

$$\delta Q_i = T_i dS_i \Rightarrow dS_i = \frac{\delta Q_i}{T_i} \quad i=1,2 \quad \left. \begin{array}{l} \delta Q_i = c_i dT_i \end{array} \right\} \boxed{dS_i = \frac{c_i}{T_i} dT_i} \quad c_i = kT_e$$

$$\boxed{dS_0 = 0} \Rightarrow dS_0 = dS_1 + dS_2 \Rightarrow dS_1 + dS_2 = 0$$

BALDINTZA!!

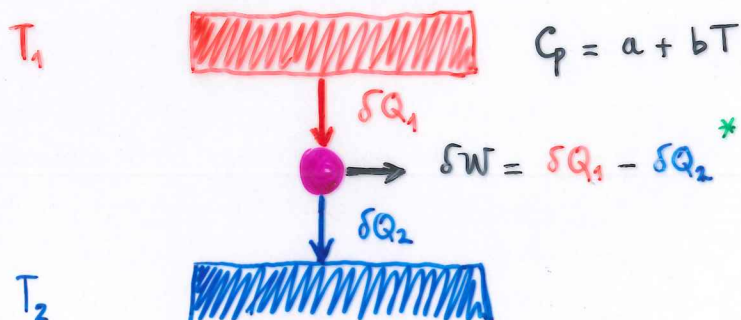
$$\frac{C_A}{T_A} dT_A + \frac{C_B}{T_B} dT_B = 0$$

$$C_A \ln \frac{T_f}{T_A} + C_B \ln \frac{T_f}{T_B} = 0 \Rightarrow \left[\frac{T_f}{T_B} \right]^{C_B} = \left[\frac{T_A}{T_f} \right]^{C_A} \Rightarrow \boxed{T_f = \left[T_B^{C_B} T_A^{C_A} \right]^{\frac{1}{C_A+C_B}}}$$

$$\left. \begin{array}{l} Q_A = -C_A (T_f - T_A) \\ Q_B = C_B (T_f - T_B) \end{array} \right\} \boxed{W = [C_A (T_f - T_A)] - [C_B (T_f - T_B)]}$$

T_f

* BALJO GUTIAK POSITIBOAK DIRA, BADAIGULAKO ZEIN NORANERKOA DIREN !!! (GERTAK)



$$\delta W = \delta Q_1 - \delta Q_2$$

$$\int \delta W = \int \delta Q_1 - \int \delta Q_2 \Rightarrow \boxed{W = Q_1 - Q_2} \quad \text{HAUXE DA KALKULATU BEHARRERKOA}$$

$$\delta Q_2 = T_2 dS_2$$

$$\boxed{dS_0 = 0} \Rightarrow dS_0 = dS_1 + dS_2 \Rightarrow -dS_1 = dS_2 \quad \left. \begin{array}{l} \\ \end{array} \right\} \boxed{\delta Q_2 = -T_2 dS_1}$$

BALDINTZA!!

$$dS_1 = \frac{C_p}{T_1} dT_1$$

$$\delta Q_2 = -T_2 \frac{C_p}{T_1} dT_1 \Rightarrow \boxed{Q_2 = -T_2 \int \frac{C_p}{T_1} dT_1}$$

ADARAKI TUTUA

$$\delta Q_1 = C_p dT_1 \Rightarrow \boxed{Q_1 = \int C_p dT_1}$$

ADARAKI TUTUA

$$\boxed{W = \left[\int C_p dT_1 \right] - \left[-T_2 \int \frac{C_p}{T_1} dT_1 \right]}$$

EMAN DUTEN DATUA (C_p) ORDEZKATU !!!

$$\left[C_p dT_1 - \left[-T_2 \int \frac{C_p}{T_1} dT_1 \right] \right]$$

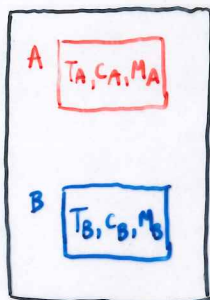
$$C_p dT_1 = -\delta Q$$

$$\left(1 - \frac{T_2}{T_1} \right) (-\delta Q)$$

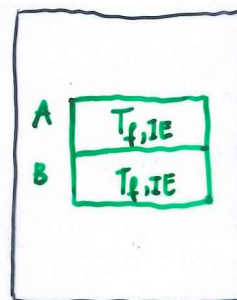
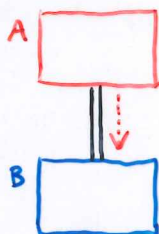
* BALIO GUZTIAK POSITIBOAK DIRA, BADA KIGULAKO ZEIN NORANZKOTARDAK DIREN !!! (GERTAK)

BI SISTEMEN ARTEKO TEMPERATURA-DIFERENTZIA : LANA EGITEKO APROBENA DAITEKE
 SISTEMEN OREKA-ESPERA : ESPERA TERMIKOA; TEMPERATURA

(i) KONTAKTU TERMIKO "ARRUNTA" : ESKUA SARTU GABE ITZULEZINA



(i)



(f)

$$Q_{osoa} = Q_A + Q_B ; Q_{osoa} = 0 \Rightarrow Q_A + Q_B = 0 \rightarrow T_f, IE$$

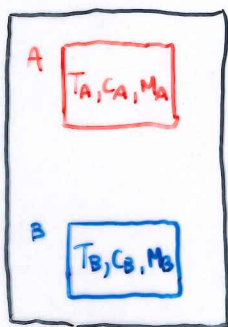
$$\Delta S_{osoa} = \Delta S_A + \Delta S_B ; \Delta S_{osoa} > 0 \Rightarrow \Delta S_A + \Delta S_B > 0$$

$$Q_i = \int_{T_i}^{T_{f, IE}} C_i dT_i$$

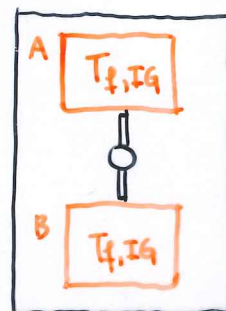
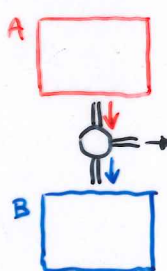
$$\Delta S_i = \int_{T_i}^{T_{f, IE}} \frac{C_i}{T_i} dT_i$$

$$\left. \begin{array}{l} \\ \end{array} \right\} i = A, B$$

(ii) KONTAKTU TERMIKO "BEREZIA" : ESKUA SARTUZ ITZULGARRIA



(i)



(f)

$$Q_{osoa} = Q_A + Q_B ; Q_{osoa} \neq 0 (\equiv W_{max}) \Rightarrow Q_A + Q_B < 0 \rightarrow T_f, IG$$

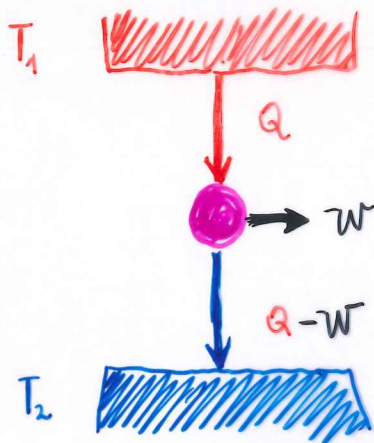
$$\Delta S_{osoa} = \Delta S_A + \Delta S_B ; \Delta S_{osoa} = 0 \Rightarrow \Delta S_A + \Delta S_B = 0$$

$$Q_i = \int_{T_i}^{T_{f, IG}} C_i dT_i$$

$$\Delta S_i = \int_{T_i}^{T_{f, IG}} \frac{C_i}{T_i} dT_i$$

$$\left. \begin{array}{l} \\ \end{array} \right\} i = A, B$$

- LAN MAXIMOA :

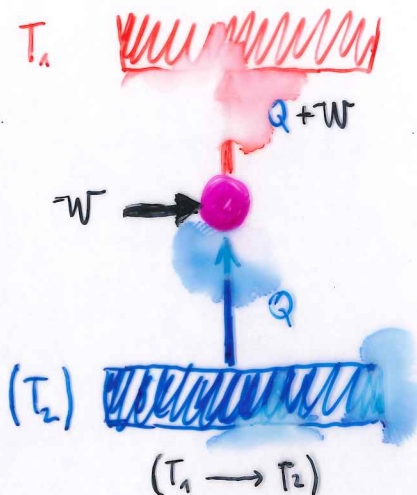


UNIBERTSOARI DABOKION ENTROPIA-ALDAKUNTZA :

$$\begin{aligned}\Delta S_u &= \Delta S_u + \Delta S_{ing} \geq 0 \\ &= 0 + (\Delta S_{T_1} + \Delta S_{T_2}) \geq 0 \quad \left(\Delta S = \frac{Q}{T}\right) \\ &= \left(-\frac{Q}{T_1} + \frac{Q-W}{T_2}\right) \geq 0\end{aligned}$$

$$W_{\max} = Q \left(1 - \frac{T_2}{T_1}\right)$$

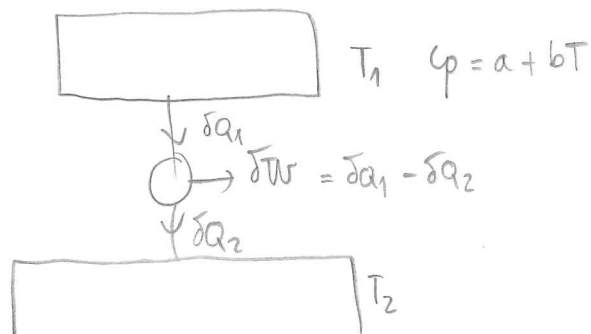
- LAN MINIMOA : GORPUZ FINITOA T_1 -ENIK T_2 -RA HOZTEKO (?)



UNIBERTSOARI DABOKION ENTROPIA-ALDAKUNTZA :

$$\begin{aligned}\Delta S_u &= \Delta S_s + \Delta S_{ing} \geq 0 \\ &= 0 + (\Delta S_{T_1} + (S_2 - S_1)) \geq 0 \\ &= + \left(\frac{Q+W}{T_1} + (S_2 - S_1)\right) \geq 0 \\ W &\geq T_1(S_2 - S_1) - Q\end{aligned}$$

$$W_{\min} = T_1(S_2 - S_1) - Q$$



$$\delta W = \delta Q_1 - \delta Q_2$$

$$\int \delta W = \int \delta Q_1 - \delta Q_2 \Rightarrow \boxed{W = Q_1 - Q_2} \text{ balio absolutuak}$$

$$\delta Q_2 = T_2 dS_2$$

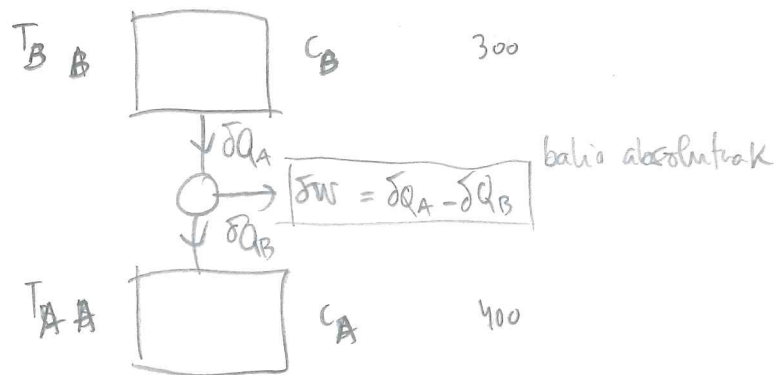
$$dS = 0 \Rightarrow dS_1 + dS_2 = 0 \Rightarrow dS_2 = -dS_1 \left. \begin{array}{l} \delta Q_2 = -T_2 dS_1 \end{array} \right\}$$

$$dS_1 = \frac{C_p}{T_1} dT_1$$

$$\delta Q_2 = -T_2 \frac{C_p}{T_1} dT_1 \Rightarrow Q_2 = -T_2 \int \frac{C_p}{T_1} dT_1 \Rightarrow \boxed{Q_2 = -T_2 C_p \ln\left(\frac{T_2}{T_1}\right)}$$

$$\delta Q_1 = C_p dT_1 \Rightarrow Q_1 = \int C_p dT \Rightarrow Q_1 = C_p \Delta T \Rightarrow \boxed{Q_1 = C_p (T_2 - T_1)}$$

$$W = C_p \left[(T_1 - T_2) + T_2 \ln\left(\frac{T_1}{T_2}\right) \right]$$



$$\left. \begin{array}{l} \delta Q_i = T_i dS_i \Rightarrow dS_i = \frac{\delta Q_i}{T_i} \quad i=1,2 \\ \delta Q_i = C_i dT_i \end{array} \right\} dS_i = \frac{C_i}{T_i} dT_i$$

$$dS = 0 \Rightarrow dS_1 + dS_2 = 0 \quad \frac{C_B}{T_B} dT_B + \frac{C_A}{T_A} dT_A = 0$$

$$\Delta S = 0 \Rightarrow C_B \ln \frac{T_f}{T_B} + C_A \ln \frac{T_f}{T_A} = 0 \Rightarrow \ln \left[\frac{T_f^{C_B}}{T_B^{C_B}} \cdot \frac{T_f^{C_A}}{T_A^{C_A}} \right] = 0$$

eta eraitzele linean

aripatu zerin den baldintza
eta zer baliatzen den

$$T_f^{C_A+C_B} = T_B^{C_B} T_A^{C_A}$$

$$\boxed{T_f = \left[T_B^{C_B} T_A^{C_A} \right]^{1/(C_A+C_B)}}$$

$$\delta W = \delta Q_1 - \delta Q_2$$

$$\int \delta W = \int \delta Q_1 - \delta Q_2 \Rightarrow W = Q_1 - Q_2$$

$$-C_B (T_f - T_B) - C_A (T_f - T_A)$$

eta gero zerua aldatu.

ENERGIA EZ ERABILGARRIA E

$$\{T, Q\}; T_0 \Rightarrow W_{\max} = Q \left(1 - \frac{T_0}{T}\right)$$

GOI-TEMPERATURAN DAGOEN BERO-ITURRITIK Q ENERGIA BERO MODUAN ATERATEAN,
ESKURA DUGUN TEMPERATURARIK BAXUENA T_0 IZANIK.

ATERA DAITEKEEN ENERGIA LAN MODUAN $W_{\max}$ LAN MAXIMOIA DA.

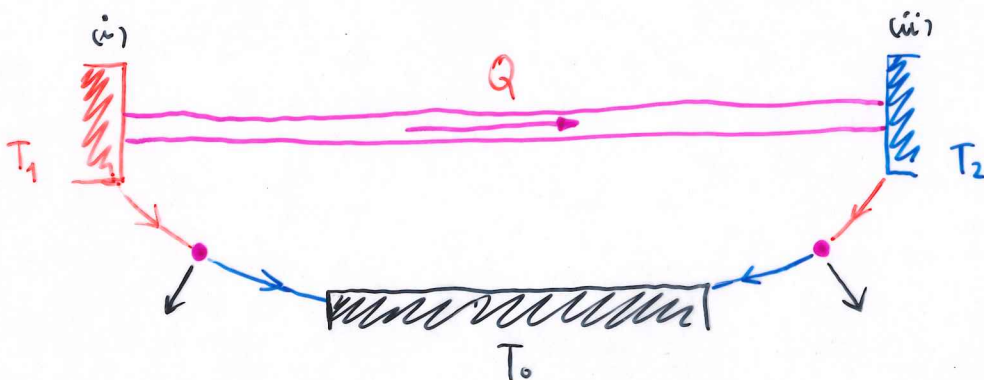
BERAHI DA LAN MODUAN ERABILTEKO ESKURA DUGUN (ESKURA DEZAKEGUN) $W_{\max}$,
HOTS; BERO ERAN SOILIK T_0 BERO-ITURRITIK ATERA DAITEKEEN ENERGIA
EZIN DA LANA ERATEKO ERABILI

ONDORIOA:

ENERGIAK BAIKU IZATERA: LANERAKO ERABIL DAITEKE
LANERAKO EZIN ERABIL DAITEKE

ZENBAT KASUTAN LANA ATERA DAITEKE ETA BESTE ZENBAT KASUTAN EZ

TEMPERATURA-GRADIENTE FINITUAREN ONDORITZKO BERO-GARRAIO ITZULEZINA:



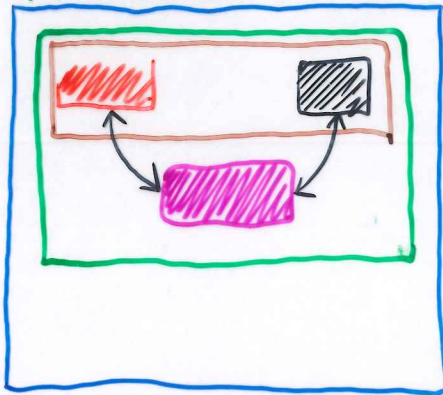
$$W_{\max}^{(i)} = Q \left(1 - \frac{T_0}{T_1}\right)$$

$$W_{\max}^{(ii)} = Q \left(1 - \frac{T_0}{T_2}\right)$$

$$E = T_0 \left(\frac{Q}{T_2} - \frac{Q}{T_1} \right)$$

$$E = T_0 \Delta S_{\text{ing}}$$

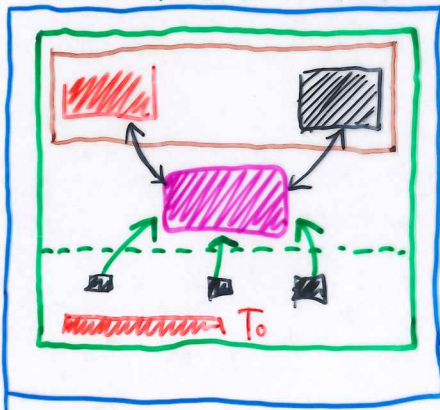
ERA ITZULEZINEAN : PROZESUA BEREZ GERTATU DA



$$Q = (U_f - U_i) - W$$

$$\Delta S_o = (S_f - S_i) + \Delta S_{\text{ing.H}} > 0 (S_f - S_i)$$

ERA ITZULGARRIAN : BEREZKO PROZESUA GERTATU DEN BERBERA, BAINA IG:



$$\Delta S_o = \{(S_f - S_i) + \Delta S_{\text{ing.H}}\} + \Delta S_{\text{ing.L}}$$

$$= (S_f - S_i) + \Delta S_{\text{ing.L}} = 0$$

$$(S_f - S_i) > 0 \Rightarrow \Delta S_{\text{ing.L}} < 0 \Rightarrow T_o \text{ BERO-ITURRIAK } E \text{ ENERGIA } (\Rightarrow)$$

BAINA AURREKO BUKAERAKO EGORRA ERAMAN BEHAR DUGUNEZ SISTEMA $(S + H)$

E ENERGIA BERORI MAKINA BERRIETARA LAN MODUAN PASATU DA, BERAZ

ESKU ARTEAN DUGUN **SISTEMA INQ. HURBILEAN** ERA ITZULEZINEAN GERTATU DIREN AIDAKETAK, ERA ITZULGARRIAN LOTZEAN, HORRETAZAKO ERABILITAKO BERO-ITURRI LAGUNAKETIK ATERAKO DEN BEROA LAN MODUAN LAN-ITURRI LAGUNERA PASATUKO DA

LAN MODUAN ERABILGARRIA ZEN
EZ DA LAN MODUAN ERABILGARRIA

$$E = T_o (S_f - S_i)$$

"GALDUTAKO ENERGIA"

EDOZEIN PROZESU ITZULEZINAREN ONDORIOZ :

UNIBERTSOAREN GAINEKO ERAGINA ONDOKO HAU DA :

LAN EGITEKO ERABILGARRIA DEN ENERGIA-KANTITATEAREN ZATIREN BAT
LAN EGITEKO EZ ERABILGARRI BIHURTUKO DA

$$E = T_0 \Delta S_u$$

LUR DAITEKEEN TEMPERATURARIK BAXUENAKO BERO-ITURRIA

ENERGIA "DEGRADATUZ" DOA !!!

